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## ON HESSIAN STRUCTURES ON THE EUCLIDEAN SPACE AND THE HYPERBOLIC SPACE

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### 1. Introduction

Let  $M$  be a manifold with a flat affine connection  $D$ . A Riemannian metric  $g$  on  $M$  is said to be a *Hessian metric* if  $g$  can be locally written  $g = D^2u$  with a local function  $u$ . We call such a pair  $(D, g)$  a *Hessian structure* on  $M$  and a triple  $(M, D, g)$  a *Hessian manifold* ([5]). Hessian structure appears in affine differential geometry and information geometry ([1], [4]).

If  $(D, g)$  is a Hessian structure on  $M$ , then in terms of an affine coordinate system  $(x^i)$  with respect to  $D$ ,  $g$  can be expressed by  $g = \sum_{i,j} (\partial^2 u / \partial x^i \partial x^j) dx^i dx^j$ . Since a Kähler metric  $h$  on a complex manifold can be locally written  $h = \sum_{i,j} (\partial^2 v / \partial z^i \partial \bar{z}^j) dz^i d\bar{z}^j$  with a local real-valued function  $v$  in terms of a complex local coordinate system  $(z^i)$ , a Hessian manifold may be regarded as a real number version of a Kähler manifold. Thus we are interested in similarity between Kähler manifolds and Hessian manifolds.

Given a complex structure on a manifold, the set of Kähler metrics is infinite-dimensional. Similarly, given a flat affine connection, the set of Hessian metrics is infinite-dimensional. We next consider the converse situation. Given a Riemannian metric  $g$ , the set of almost complex structures  $J$  that makes  $g$  into a Kähler metric is finite-dimensional because  $J$  is parallel with respect to the Riemannian connection. As a Hessian structure version of this, a question arises whether the set of flat affine connections that makes a given Riemannian metric into a Hessian metric is finite-dimensional. In this paper, we shall show that in the cases of the Euclidean space  $(\mathbf{R}^n, g_0)$  and the hyperbolic space  $(H^n, g_0)$ , the set of such connections is infinite-dimensional.

We prepare the terminology and notation. Let  $(M, g)$  be a Riemannian manifold of dimension  $\geq 2$  and  $S^3(M)$  the space of all symmetric covariant tensor fields of degree 3 on  $M$ . We denote by  $R$  and  $\nabla$  the curvature tensor and the Riemannian connection, respectively. If  $D$  is a flat affine connection of  $M$  that makes  $g$  into a Hessian metric, then the covariant tensor  $T$  corresponding to  $\hat{T} = D - \nabla$  by  $g$  is an element of  $S^3(M)$  satisfying  $R^{\nabla+\hat{T}} = 0$  on  $M$ . Conversely, if the tensor  $\hat{T}$  of type  $(1, 2)$  corresponding to  $T \in S^3(M)$  by  $g$  satisfies  $R^{\nabla+\hat{T}} = 0$  on  $M$ , then  $D = \nabla + \hat{T}$  defines

the connection above. By this relation, there is a one-to-one correspondence between the set of flat affine connections of  $M$  that makes  $g$  into a Hessian metric and the set of  $T \in S^3(M)$  satisfying  $R^{\nabla+\hat{T}} = 0$  on  $M$ . So we say that  $T \in S^3(M)$  generates a Hessian structure with  $g$  on  $M$  if  $R^{\nabla+\hat{T}} = 0$  on  $M$  and indicate by  $\mathcal{H}(M, g)$  the set of such tensors. To consider a local problem, we also define the set  $\mathcal{H}(x, g)$  by the set of symmetric covariant tensors of degree 3 defined on a neighborhood of a point  $x \in M$  generating a Hessian structure with  $g$  on its domain of definition, where we identify two elements coinciding on a sufficiency small neighborhood of  $x$ .

Roughly speaking, we shall prove the following:

**Theorem 1.1.** *The set  $\mathcal{H}(0, g_0)$  at the origin 0 of  $\mathbf{R}^2$  has the freedom of three local functions on  $\mathbf{R}$ .*

**Corollary 1.2.** *The set  $\mathcal{H}(\mathbf{R}^n, g_0)$  has at least the freedom of  $n$  functions on  $\mathbf{R}$ . In particular, the set  $\mathcal{H}(T^n, g_0)$  on the  $n$ -torus  $T^n$  has at least the freedom of  $n$  periodic functions on  $\mathbf{R}$ .*

**Theorem 1.3.** *The set  $\mathcal{H}(H^n, g_0)$  has at least the freedom of  $n - 1$  functions on  $\mathbf{R}$ .*

## 2. Euclidean case

In this section, we shall show Theorem 1.1 and Corollary 1.2.

**Lemma 2.1.** *Let  $T$  be an element of  $S^3(M)$  with components  $T_{ijk}$ . Then,  $T$  generates a Hessian structure with  $g$  on  $M$  if and only if*

$$(2.1) \quad \nabla_k T_{ijl} = \nabla_l T_{ijk},$$

$$(2.2) \quad R_{ijkl}^{\nabla} + \sum_s (T_{iks} T_{jl}^s - T_{ils} T_{jk}^s) = 0.$$

*Proof.* By definition,  $T$  generates a Hessian structure with  $g$  on  $M$  if and only if the tensor  $\hat{T}$  of type (1, 2) corresponding to  $T$  by  $g$  satisfies  $R^{\nabla+\hat{T}} = 0$  on  $M$ . In terms of  $T_{ijk}$ ,  $R^{\nabla+\hat{T}} = 0$  may be expressed by

$$R_{ijkl}^{\nabla} + \nabla_k T_{ijl} - \nabla_l T_{ijk} + \sum_s (T_{iks} T_{jl}^s - T_{ils} T_{jk}^s) = 0.$$

Subtracting this from the one exchanged  $i$  and  $j$  in this, we get (2.2) and hence (2.1).  $\square$

Applying Lemma 2.1 to Euclidean case, we have

**Lemma 2.2.** *Let  $U$  be a simply connected neighborhood of the origin  $0$  of the Euclidean space  $\mathbf{R}^n$  and  $T$  an element of  $S^3(U)$ . Let  $T_{ijk}$  be the components of  $T$  with respect to the natural coordinate system  $x^1, \dots, x^n$  in  $\mathbf{R}^n$ . Then,  $T$  generates a Hessian structure on  $U$  if and only if there exists a function  $u$  on  $U$  such that*

$$(2.3) \quad T_{ijk} = \frac{\partial^3 u}{\partial x^i \partial x^j \partial x^k},$$

$$(2.4) \quad \sum_{s=1}^n \frac{\partial^3 u}{\partial x^i \partial x^k \partial x^s} \frac{\partial^3 u}{\partial x^j \partial x^l \partial x^s} = \sum_{s=1}^n \frac{\partial^3 u}{\partial x^i \partial x^l \partial x^s} \frac{\partial^3 u}{\partial x^j \partial x^k \partial x^s}.$$

*Proof.* We obtain  $\partial T_{ijl} / \partial x^k = \partial T_{ijk} / \partial x^l$  on  $U$  from (2.1). Thus by Poincaré's lemma, there exists a function  $u_{ij}$  on  $U$  such that  $T_{ijk} = \partial u_{ij} / \partial x^k$ . Moreover, because  $\partial u_{ij} / \partial x^k = \partial u_{ik} / \partial x^j$  from the symmetry of  $T$ , again by Poincaré's lemma, there exists a function  $u_i$  on  $U$  such that  $T_{ijk} = \partial^2 u_i / \partial x^j \partial x^k$ . Once again by using the symmetry of  $T$  and Poincaré's lemma, finally we get  $T_{ijk} = \partial^3 u / \partial x^i \partial x^j \partial x^k$ . Substituting this to (2.2), we have (2.4).  $\square$

By Lemma 2.2, we see that, up to the quadratic functions of  $x^1, \dots, x^n$ , there is a one-to-one correspondence between the solutions  $u$  of (2.4) on a neighborhood of  $0 \in \mathbf{R}^n$  and  $\mathcal{H}(0, g_0)$  at  $0 \in \mathbf{R}^n$  by  $u \mapsto (\partial^3 u / \partial x^i \partial x^j \partial x^k)$ . So we investigate equation (2.4) in a neighborhood of  $0 \in \mathbf{R}^n$ .

In case  $n = 2$ , (2.4) is reduced to the only one equation:

$$u_{xxx}u_{xyy} + u_{yyy}u_{yxx} = u_{yxx}^2 + u_{xyy}^2,$$

where  $x = x^1, y = x^2$ . Then

$$\begin{aligned} 0 &= (u_{xxx} - u_{xyy})u_{xyy} + (u_{yyy} - u_{yxx})u_{yxx} \\ &= (u_{xx} - u_{yy})_x (u_{xy})_y - (u_{xx} - u_{yy})_y (u_{xy})_x \\ &= \begin{vmatrix} (u_{xx} - u_{yy})_x & (u_{xx} - u_{yy})_y \\ (u_{xy})_x & (u_{xy})_y \end{vmatrix}. \end{aligned}$$

This is equivalent to having a functional relation

$$F(u_{xx} - u_{yy}, u_{xy}) = 0$$

on a neighborhood of  $0 \in \mathbf{R}^2$ , where  $F = F(s, t)$  is an arbitrary function satisfying  $F_s^2 + F_t^2 \neq 0$ . Furthermore, this can be written

$$(2.5) \quad u_{xx} - u_{yy} = f(u_{xy}) \quad \text{if } F_s \neq 0$$

and

$$(2.6) \quad u_{xy} = \hat{f}(u_{xx} - u_{yy}) \quad \text{if } F_t \neq 0.$$

Since (2.6) is reduced to the type of (2.5):  $u_{\xi\xi} - u_{\eta\eta} = \hat{f}(4u_{\xi\eta})$  by the change of variables  $\xi = x + y$ ,  $\eta = x - y$ , we study (2.5).

We know by the following theorem that (2.5) has a unique solution  $u(x, y)$  for any given initial data  $(u(0, y), u_x(0, y))$ :

**Fact ([2]).** *Let  $u_0(y)$ ,  $u_1(y)$  and  $A(x, y, u, p, q, s, t)$  are smooth functions. Then, Cauchy problem*

$$\begin{cases} u_{xx} = A(x, y, u, u_x, u_y, u_{xy}, u_{yy}) \\ u(0, y) = u_0(y), \quad u_x(0, y) = u_1(y) \end{cases}$$

has a unique solution  $u(x, y)$  on a neighborhood of  $x = 0$  if its linearized equation

$$u_{xx} - au_{xy} - bu_{yy} - (\text{the terms of lower order}) = 0$$

with coefficients

$$\begin{aligned} a(x, y) &= A_s(x, y, U, U_x, U_y, U_{xy}, U_{yy}), \\ b(x, y) &= A_t(x, y, U, U_x, U_y, U_{xy}, U_{yy}), \end{aligned}$$

where  $U(x, y) = u_0(y) + xu_1(y)$ , is hyperbolic.

We check that the linearized equation of (2.5) is hyperbolic for any functions  $u_0(y)$ ,  $u_1(y)$ . We need to verify that its characteristic equation  $\lambda^2 - a\xi\lambda - b\xi^2 = 0$  has two different real roots  $\lambda_1$ ,  $\lambda_2$ , i.e., its discriminant is positive for any real number  $\xi \neq 0$ . We get  $a(x, y) = f'(u'_1(y))$  and  $b(x, y) = 1$ . Thus the characteristic equation is written  $\lambda^2 - f'(u'_1(y))\xi\lambda - \xi^2 = 0$ . Then because the discriminant is computed as  $(f'(u'_1(y))\xi)^2 + 4\xi^2 = \xi^2(f'(u'_1(y))^2 + 4)$ , it is positive for any  $\xi \neq 0$ .

Consequently we have a bijection from the solutions  $u$  of  $F(u_{xx} - u_{yy}, u_{xy}) = 0$  with  $F_s \neq 0$  into the triples of local functions on  $\mathbf{R}$  by  $u \mapsto (f, u(0, y), u_x(0, y))$ . Therefore we obtain

**Theorem 1.1.** *The set  $\mathcal{H}(0, g_0)$  at the origin 0 of  $\mathbf{R}^2$  can be expressed by the union of two sets each of which is in one-to-one correspondence with the set of triples of local functions on  $\mathbf{R}$  up to finite-dimensional factor.*

Now setting  $\hat{f} = 0$  at (2.6), we get  $u_{xy} = 0$  and, from this,  $u = \varphi_1(x) + \varphi_2(y)$  with arbitrary functions  $\varphi_1$ ,  $\varphi_2$ . If they are global functions on  $\mathbf{R}$ , this is a global solution of (2.4) on  $\mathbf{R}^2$ . Especially, if they are periodic, this is one on 2-torus  $T^2$ .

Hence we have an injection from the pairs of functions on  $\mathbf{R}$  into  $\mathcal{H}(\mathbf{R}^2, g_0)$  by  $(\varphi_1, \varphi_2) \mapsto (\partial^3(\varphi_1(x^1) + \varphi_2(x^2))/\partial x^i \partial x^j \partial x^k)$ . Restricting it on the periodic ones, we also obtain a mapping into  $\mathcal{H}(T^2, g_0)$ .

We prove the following lemma to generalize this:

**Lemma 2.3.** *If  $u$  is a solution of (2.4) on  $\mathbf{R}^n$  and  $v$  is an arbitrary function on  $\mathbf{R}$ , then  $u(x_1, \dots, x_n) + v(x_{n+1})$  is a solution of (2.4) on  $\mathbf{R}^{n+1}$ .*

*Proof.* We have to establish

$$(2.7) \quad \sum_{s=1}^{n+1} \partial_i \partial_k \partial_s (u + v) \partial_j \partial_l \partial_s (u + v) = \sum_{s=1}^{n+1} \partial_i \partial_l \partial_s (u + v) \partial_j \partial_k \partial_s (u + v),$$

where we write  $\partial_i$  for  $\partial/\partial x^i$ . We may assume  $i < j$ ,  $k < l$  at (2.7) from symmetry. Then  $i, k \neq n + 1$  and

$$\begin{aligned} & \text{the left-hand side of (2.7)} \\ &= \sum_{s=1}^{n+1} (\partial_i \partial_k \partial_s u \partial_j \partial_l \partial_s u + \partial_i \partial_k \partial_s u \partial_j \partial_l \partial_s v + \partial_i \partial_k \partial_s v \partial_j \partial_l \partial_s u + \partial_i \partial_k \partial_s v \partial_j \partial_l \partial_s v) \\ &= \left( \sum_{s=1}^n \partial_i \partial_k \partial_s u \partial_j \partial_l \partial_s u \right) + \partial_i \partial_k v' \partial_j \partial_l v' \\ &= \sum_{s=1}^n \partial_i \partial_k \partial_s u \partial_j \partial_l \partial_s u. \end{aligned}$$

Similarly

$$\text{the right-hand side of (2.7)} = \sum_{s=1}^n \partial_i \partial_l \partial_s u \partial_j \partial_k \partial_s u.$$

Since  $u$  is a solution of (2.4) on  $\mathbf{R}^n$  by the assumption, both sides are equal to one another.  $\square$

Combining the result of 2-dimensional case and Lemma 2.3, we obtain

**Corollary 1.2.** *The mapping  $\Phi : (\varphi_1, \dots, \varphi_n) \mapsto (\partial^3(\varphi_1(x^1) + \dots + \varphi_n(x^n))/\partial x^i \partial x^j \partial x^k)$  gives an injection from the set of  $n$ -tuples of functions on  $\mathbf{R}$  into the set  $\mathcal{H}(\mathbf{R}^n, g_0)$  up to finite-dimensional factor. Particularly,  $\Phi$  restricted on the set of periodic ones gives a mapping into the set  $\mathcal{H}(T^n, g_0)$  on  $n$ -torus  $T^n$ .*

### 3. Hyperbolic case

In this section, we shall show Theorem 1.3.

We set

$$H^n = \{(x^1, \dots, x^n) \in \mathbf{R}^n | x^n > 0\} \quad \text{and} \quad g_0 = \frac{1}{(x^n)^2} \{(dx^1)^2 + \dots + (dx^n)^2\}.$$

It is known that there exists an element  $T_0 = ((T_0)_{ijk}) \in S^3(H^n)$  generating a Hessian structure with  $g_0$  on  $H^n$ , which is given for  $1 \leq i \leq j \leq k \leq n$  as follows ([3]):

$$(T_0)_{ijk} = \begin{cases} \frac{1}{(x^n)^3} & 1 \leq i = j \leq n-1, k = n \\ \frac{2}{(x^n)^3} & i = j = k = n \\ 0 & \text{otherwise.} \end{cases}$$

We consider the case  $n = 2$  for a while.

An element  $X$  of  $S^3(M)$  is called an *infinitesimal deformation* of  $T \in \mathcal{H}(M, g)$  if  $(d/dt)|_{t=0} R^{\nabla+T+tX} = 0$ .

**Lemma 3.1.** *An infinitesimal deformation  $X = (X_{ijk}) \in S^3(H^2)$  of  $T_0 \in \mathcal{H}(H^2, g_0)$  is given by*

$$(3.1) \quad X_{111} = \frac{f''(x)y^2}{8} + \frac{g'(x)}{2} - f(x) + \frac{h(x)}{y^2},$$

$$(3.2) \quad X_{112} = \frac{f'(x)y}{2} + \frac{g(x)}{y},$$

$$(3.3) \quad X_{122} = f(x),$$

$$(3.4) \quad X_{222} = 0,$$

where  $x = x^1$ ,  $y = x^2$ , and  $f, g, h$  are arbitrary functions.

*Proof.* In general, by differentiating each of ones substituted  $T + tX$  for  $T$  in (2.1) and (2.2), we obtain equations for an infinitesimal deformation  $X$  of  $T \in \mathcal{H}(M, g)$  as follows:

$$\begin{aligned} \nabla_k X_{ijl} - \nabla_l X_{ijk} &= 0, \\ \sum_s (X_{iks} T_{jl}^s + T_{iks} X_{jl}^s - X_{ils} T_{jk}^s - T_{ils} X_{jk}^s) &= 0. \end{aligned}$$

In case  $(M, g) = (H^2, g_0)$  and  $T = T_0$ , this is reduced to

$$(3.5) \quad (X_{111})_y - (X_{112})_x + \frac{2}{y}(X_{111} + X_{122}) = 0$$

$$(3.6) \quad (X_{112})_y - (X_{122})_x + \frac{1}{y}X_{112} = 0,$$

$$(3.7) \quad (X_{122})_y = 0,$$

$$(3.8) \quad X_{222} = 0.$$

First from (3.7), we get (3.3). Then equation (3.6) is written as

$$(X_{112})_y + \frac{1}{y}X_{112} = f'(x).$$

Solving this, we have (3.2). Finally by (3.2) and (3.3), equation (3.5) is written as

$$(X_{111})_y + \frac{2}{y}X_{111} = \frac{f''(x)y}{2} + \frac{g'(x)}{y} - 2\frac{f(x)}{y}.$$

Solving this, we obtain (3.1). □

We find out the elements of  $\mathcal{H}(H^2, g_0)$  that has the form of  $T_0 + X$ . Since both of  $T_0$  and  $X$  satisfy (2.1),  $T_0 + X$  satisfies it. Thereby  $T_0 + X$  belongs to  $\mathcal{H}(H^2, g_0)$  if and only if it satisfies (2.2) in  $H^2$ . In the present case, it is reduced to the only one equation:

$$X_{111}X_{122} + X_{222}X_{112} - X_{112}^2 - X_{122}^2 = 0.$$

Substituting (3.1) ~ (3.4), we get

$$\begin{aligned} 0 &= \left( \frac{f''(x)y^2}{8} + \frac{g'(x)}{2} - f(x) + \frac{h(x)}{y^2} \right) f(x) - \left( \frac{f'(x)y}{2} + \frac{g(x)}{y} \right)^2 - f(x)^2 \\ &= \left( \frac{f(x)f''(x)}{8} - \frac{f'(x)^2}{4} \right) y^2 + \frac{f(x)g'(x)}{2} \\ &\quad - f'(x)g(x) - 2f(x)^2 + (f(x)h(x) - g(x)^2) \frac{1}{y^2}. \end{aligned}$$

Hence  $T_0 + X$  belongs to  $\mathcal{H}(H^2, g_0)$  if and only if

$$(3.9) \quad ff'' - 2f'^2 = 0,$$

$$(3.10) \quad fg' - 2f'g - 4f^2 = 0,$$

$$(3.11) \quad fh - g^2 = 0.$$

We find the global solutions of this:

A. The case  $f = 0$ .



From (3.11), we have  $g = 0$ . So the solution is

$$\begin{cases} f = 0 \\ g = 0 \\ h: \text{an arbitrary function.} \end{cases}$$

B. The case  $f \neq 0$ .

By supposing  $f' \neq 0$ , (3.9) can be written

$$\frac{f''}{f'} = 2\frac{f'}{f}.$$

From this, we obtain  $f = 1/(Ax + B)$  with arbitrary constants  $A, B$ . Then  $f$  is a global solution if and only if  $A = 0$  and  $B \neq 0$ . But this contradicts with  $f' \neq 0$ . Thus  $f' = 0$ , i.e.,  $f$  is a constant. Setting  $f = C_1 (\neq 0)$ , from (3.10) and (3.11), we get  $g = 4C_1x + C_2$  and  $h = g^2/C_1$ . So the solution is

$$\begin{cases} f = C_1 \\ g = 4C_1x + C_2 \\ h = \frac{g^2}{C_1}. \end{cases}$$

Therefore we have

**Proposition 3.2.** For an infinitesimal deformation  $X = (X_{ijk}) \in S^3(H^2)$  of  $T_0 \in \mathcal{H}(H^2, g_0)$ ,  $T_0 + X$  belongs to  $\mathcal{H}(H^2, g_0)$  if and only if  $X$  is given as follows:

$$(3.12) \quad \begin{cases} X_{111} = \frac{h(x)}{y^2} \\ X_{112} = 0 \\ X_{122} = 0 \\ X_{222} = 0 \end{cases}$$

or

$$(3.13) \quad \begin{cases} X_{111} = C_1 + \frac{(4C_1x + C_2)^2}{C_1y^2} \\ X_{112} = \frac{4C_1x + C_2}{y} \\ X_{122} = C_1 \\ X_{222} = 0, \end{cases}$$

where  $h$  is an arbitrary function and  $C_1 \neq 0$  and  $C_2$  are arbitrary constants.

We go back to the general case. On the analogy of (3.12), we obtain

**Theorem 1.3.** *Let  $\tilde{X} = (\tilde{X}_{ijk}) \in S^3(H^n)$  be given by*

$$\tilde{X}_{ijk} = \begin{cases} \frac{f_i(x^i)}{(x^n)^2} & 1 \leq i = j = k \leq n-1 \\ 0 & \text{otherwise,} \end{cases}$$

where  $f_i$  are arbitrary functions. Then,  $T_0 + \tilde{X}$  belongs to  $\mathcal{H}(H^n, g_0)$ .

*Proof.* We prove that  $T_0 + \tilde{X}$  satisfies (2.1) and (2.2). We first verify to satisfy (2.1). Because  $T_0$  satisfies it, we need only verify that  $\tilde{X}$  satisfies it, that is,

$$(3.14) \quad \partial_k \tilde{X}_{ijl} - \partial_l \tilde{X}_{ijk} + \sum_s (\Gamma_l^s \tilde{X}_{sjk} + \Gamma_l^s \tilde{X}_{isk} - \Gamma_k^s \tilde{X}_{sjl} - \Gamma_k^s \tilde{X}_{isl}) = 0,$$

where the Christoffel symbols  $\Gamma_j^i{}^k$  of  $\nabla$  is given by

$$\Gamma_j^i{}^k = \begin{cases} \frac{1}{x^n} & i = n, 1 \leq j = k \leq n-1 \\ \frac{-1}{x^n} & 1 \leq i = j \leq n-1, k = n; \text{ or } i = j = k = n \\ 0 & \text{otherwise.} \end{cases}$$

It suffices to consider (3.14) for  $i \leq j, k < l$  by symmetry.

A. The case  $i = j$ .

Then

$$\begin{aligned} \text{the left-hand side of (3.14)} &= \partial_k \tilde{X}_{iil} - \partial_l \tilde{X}_{iik} + 2 \sum_s (\Gamma_l^s \tilde{X}_{sik} - \Gamma_k^s \tilde{X}_{sil}) \\ &= \partial_k \tilde{X}_{iil} - \partial_l \tilde{X}_{iik} + 2 \sum_s \Gamma_l^s \tilde{X}_{sik}. \end{aligned}$$

If  $i = k$ , then we get

$$\begin{aligned} \partial_k \tilde{X}_{iil} - \partial_l \tilde{X}_{iik} + 2 \sum_s \Gamma_l^s \tilde{X}_{sik} &= -\partial_l \tilde{X}_{iii} + 2 \sum_s \Gamma_l^s \tilde{X}_{sii} \\ &= -\partial_l \frac{f_i(x^i)}{(x^n)^2} + 2\Gamma_l^i \tilde{X}_{iii} \\ &= \begin{cases} 2\Gamma_l^i \tilde{X}_{iii} = 0 & l < n \\ 2\frac{f_i(x^i)}{(x^n)^3} + 2\frac{-1}{x^n} \frac{f_i(x^i)}{(x^n)^2} = 0 & l = n. \end{cases} \end{aligned}$$

If  $i \neq k$ , then we have

$$\partial_k \tilde{X}_{iil} - \partial_l \tilde{X}_{iik} + 2 \sum_s \Gamma_l^s \tilde{X}_{sik} = \partial_k \tilde{X}_{iil} = \delta_{il} \partial_k \frac{f_i(x^i)}{(x^n)^2} = 0,$$

where  $\delta_{ij}$  is Kronecker's delta.

B. The case  $i < j$ .

Then

$$\begin{aligned} \text{the left-hand side of (3.14)} &= \sum_s (\Gamma_l^s \tilde{X}_{sjk} + \Gamma_l^s \tilde{X}_{isk} - \Gamma_k^s \tilde{X}_{sjl} - \Gamma_k^s \tilde{X}_{isl}) \\ &= \sum_s (\Gamma_l^s \tilde{X}_{sjk} + \Gamma_l^s \tilde{X}_{isk} - \Gamma_k^s \tilde{X}_{isl}). \end{aligned}$$

Since (3.14) is equal to the one exchanged a pair  $(i, j)$  and a pair  $(k, l)$ , we need only check the following three cases:

If  $i = k, j = l$ , then we obtain

$$\begin{aligned} \sum_s (\Gamma_l^s \tilde{X}_{sjk} + \Gamma_l^s \tilde{X}_{isk} - \Gamma_k^s \tilde{X}_{isl}) &= \sum_s (\Gamma_j^s \tilde{X}_{sji} + \Gamma_j^s \tilde{X}_{isi} - \Gamma_i^s \tilde{X}_{isj}) \\ &= \sum_s \Gamma_j^s \tilde{X}_{isi} \\ &= \Gamma_j^i \tilde{X}_{iii} \\ &= 0. \end{aligned}$$

If  $i = k, j < l$ , then we get

$$\begin{aligned} \sum_s (\Gamma_l^s \tilde{X}_{sjk} + \Gamma_l^s \tilde{X}_{isk} - \Gamma_k^s \tilde{X}_{isl}) &= \sum_s (\Gamma_l^s \tilde{X}_{sji} + \Gamma_l^s \tilde{X}_{isi} - \Gamma_i^s \tilde{X}_{isl}) \\ &= \sum_s \Gamma_l^s \tilde{X}_{isi} \\ &= \Gamma_l^i \tilde{X}_{iii} \\ &= 0. \end{aligned}$$

If  $i < k$ , then we have

$$\begin{aligned} \sum_s (\Gamma_l^s \tilde{X}_{sjk} + \Gamma_l^s \tilde{X}_{isk} - \Gamma_k^s \tilde{X}_{isl}) &= \sum_s \Gamma_l^s \tilde{X}_{sjk} \\ &= \begin{cases} \Gamma_l^i \tilde{X}_{njk} = 0 & l < n \\ \Gamma_n^i \tilde{X}_{ijk} = 0 & l = n. \end{cases} \end{aligned}$$

We next establish that  $\tilde{T} = T_0 + \tilde{X}$  satisfies (2.2), i.e.,

$$(3.15) \quad \sum_s (\tilde{T}_{iks} \tilde{T}_{jls} - \tilde{T}_{ils} \tilde{T}_{jks}) = \frac{1}{(x^n)^6} (\delta_{ik} \delta_{jl} - \delta_{il} \delta_{jk}),$$

where  $\tilde{T} = (\tilde{T}_{ijk})$  is given by

$$\tilde{T}_{ijk} = \begin{cases} \frac{1}{(x^n)^3} & 1 \leq i = j \leq n-1, k = n \\ \frac{f_i(x^i)}{(x^n)^2} & 1 \leq i = j = k \leq n-1 \\ \frac{2}{(x^n)^3} & i = j = k = n \\ 0 & \text{otherwise.} \end{cases}$$

It suffices to consider (3.15) in the case  $i = k, j = l$ , in the case  $i = k, j < l$  and in the case  $i < k$  under  $1 \leq i < j \leq n, 1 \leq k < l \leq n$  from symmetry.

A. The case  $i = k, j = l$ .

Equality (3.15) is written as

$$(3.16) \quad \sum_s (\tilde{T}_{iis} \tilde{T}_{jjs} - \tilde{T}_{ijs}^2) = \frac{1}{(x^n)^6}.$$

Then

$$\begin{aligned} \text{the left-hand side of (3.16)} &= \tilde{T}_{iii} \tilde{T}_{jji} + \tilde{T}_{iin} \tilde{T}_{jjn} - \tilde{T}_{iji}^2 \\ &= \tilde{T}_{iin} \tilde{T}_{jjn} - \tilde{T}_{ijj}^2 \\ &= \begin{cases} \frac{1}{(x^n)^3} \frac{1}{(x^n)^3} = \frac{1}{(x^n)^6} & j < n \\ \frac{1}{(x^n)^3} \frac{2}{(x^n)^3} - \left( \frac{1}{(x^n)^3} \right)^2 = \frac{1}{(x^n)^6} & j = n. \end{cases} \end{aligned}$$

B. The case  $i = k, j < l$ .

Equality (3.15) is simplified as

$$(3.17) \quad 0 = \sum_s (\tilde{T}_{iis} \tilde{T}_{jls} - \tilde{T}_{ils} \tilde{T}_{jis}) = \sum_s \tilde{T}_{iis} \tilde{T}_{jls}.$$

Then

$$\text{the right-hand side of (3.17)} = \tilde{T}_{iii} \tilde{T}_{jli} + \tilde{T}_{iin} \tilde{T}_{jln} = 0.$$

C. The case  $i < k$ .

Equality (3.15) is simplified as

$$(3.18) \quad 0 = \sum_s (\tilde{T}_{iks} \tilde{T}_{jls} - \tilde{T}_{ils} \tilde{T}_{jks}) = - \sum_s \tilde{T}_{ils} \tilde{T}_{jks}.$$

Then

$$\text{the right-hand side of (3.18)} = -\tilde{T}_{ili} \tilde{T}_{jki} = 0. \quad \square$$

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