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Title	In-Hand Rolling Manipulation Based on Ball-on-Cloth System
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Note	

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Supplementary Note on Related Work

After the publication of the Version of Record (VOR), we became aware of relevant related work. We provide the following supplementary note in this repository.

In related work, Hunte et al. proposed methods for manipulating spherical objects on a deformable sheet held by multiple mobile robots [add-1, add-2]. Their approaches geometrically model the sphere-sheet system primarily based on the center position of the sphere.

[add-1] Kyle Hunte, Jingang Yi, "Collaborative Manipulation of Spherical-Shape Objects with a Deformable Sheet Held by a Mobile Robotic Team," IFAC-PapersOnLine, Volume 54, Issue 20, 2021, Pages 437-442.

[add-2] Kyle Hunte, Jingang Yi, "Pose Control of a Spherical Object Held by Deformable Sheet with Multiple Robots," IFAC-PapersOnLine, Volume 55, Issue 37, 2022, Pages 414-419.

In contrast, this paper discusses an in-hand manipulation problem and considers the size of the ball and the adaptive deformation of the cloth along the spherical surface.

This supplementary note is intended to provide additional context on the positioning and contributions of our work. It does not affect the results, analysis, or conclusions of the original paper.