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TENSOR PRODUCT AND GENERALIZED OTT-SCHAEFFER PLANES

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1. Introduction

The Ott-Schaeffer planes (O-S) are translation planes of even order q^2 with kernel $K \cong GF(q)$ which admit a collineation group \mathcal{G} isomorphic to SL(2, q) where the involutions are Baer. Furthermore, if \mathcal{S}_2 is a Sylow 2-subgroup of \mathcal{G} then no two nontrivial elements of \mathcal{G} fix the same Baer subplane pointwise.

The O-S planes are also derivable and a plane may be defined for each automorphism α of GF(q), $q=2^{2r+1}$ which has fixed field equal to GF(2). Hence, the number of such translation planes of each order is $\Phi(2r+1)$ (the number of integers ± 1 relatively prime to 2r+1).

Further, the O-S planes may be defined by the tensor product of SL(2, q) by a twisted version of the same (by an automorphism $\alpha \ni \text{Fix } \alpha = GF(2)$).

Note that $GL(2, q) = SL(2, q) \times \mathbb{Z}(GL(2, q))$ (center) when q is even so as the kernel is GF(q), the O-S planes also admit GL(2, q).

Conversely, in [7], for arbitrary kernel we have

Theorem (Johnson [7]). Let π be a translation plane of even order $q^2 > 16$ that admits GL(2, q) as a collineation group in the translation complement where the 2-groups are Baer and no two nontrivial elements fix the same Baer subplane pointwise. Then π is an Ott-Schaeffer plane.

DEFINITION 1.1. Tensor Product Plane.

A translation plane π of order q^2 , q even or odd, kernel $K \cong GF(q)$ that admits the collineation group

$$T = \left\{ \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \middle| a \in K \right\}, \ \sigma \in \text{Aut } K$$

where $\pi = \{(x_1, x_2, y_1, y_2) | x_i, y_i \in K, i=1, 2\}, x=(x_1, x_2), y=(y_1, y_2) \text{ and } x=0, y=0, y=x \text{ are components in this representation is called a$ *tensor product plane*.

DEFINITION 1.2. Generalized Ott-Schaeffer Plane.

A translation plane π of order q^2 , q even or odd, $q=p^r$ for p a prime, kernel

 $K \simeq GF(q)$, that admits a *p*-group \mathscr{B} of order *q* in the translation complement such that each element of \mathscr{B} is Baer and no two nontrivial subgroups of \mathscr{B} can fix the same Baer subplane pointwise is called a *generalized Ott-Schaeffer plane*.

In section 2, we consider the basic structure of tensor product planes and of generalized Ott-Schaeffer planes. In section 3, we consider translation planes (T-P and O-S) which admit groups of order q(q-1) in the translation complement.

Our main results completely classify both tensor product planes of even order q^2 admitting a tensor group of order q(q-1) (see (3.4)) and generalized Ott-Schaeffer planes admitting groups of order q(q-1) in the translation complement with prescribed Sylow 2 subgroups (see (3.21)).

2. The fundamental structure

NOTES 2.1. For q odd $q=p^r$, $p \ge 3$, there is no tensor product plane. If $p \ge 5$ there is no generalized Ott-Schaeffer plane of order q^2 .

Proof. Consider

$$\tau_{a} = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a^{\sigma} & a & a^{\sigma+1} \\ 0 & 1 & 0 & a \\ 0 & 0 & 1 & a^{\sigma} \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

 $\tau_a(a \neq 0)$ fixes $\pi_a = \{(0, x_2, -x_2 a^{1-\sigma}, y_2) | (x_2, y_2) | x_2, y_2 \in K\}$ pointwise. Furthermore, $\{\tau_a | a \in K \cong GF(q)\} = S_p$ is elementary abelian. By Foulser [4], S_p must fix some Baer subplane pointwise, which cannot be the case. Hence, there are no tensor product planes of characteristic ≥ 5 .

Now assume p=3. The components x=0, y=xM of π_a , for $M=\begin{bmatrix} m_1 & m_2 \\ m_3 & m_4 \end{bmatrix}$, must satisfy $(0, x_2, x_2m_3, x_2m_4)=(0, x_2, -x_2a^{1-\sigma}, y_2)$ so that $m_3=-a^{1-\sigma}$.

On the other hand, in order that y=xM is fixed by τ_a , we must have

$$\begin{bmatrix} x \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}, x \begin{bmatrix} \begin{bmatrix} a & a^{\sigma+1} \\ 0 & a \end{bmatrix} + M \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \end{bmatrix} \in y = xM$$

$$\Rightarrow \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \begin{bmatrix} m_1 & m_2 \\ -a^{1-\sigma} & m_4 \end{bmatrix} = \begin{bmatrix} a & a^{\sigma+1} \\ 0 & a \end{bmatrix} + \begin{bmatrix} m_1 & m_2 \\ -a^{1-\sigma} & m_4 \end{bmatrix} \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}$$

$$\Rightarrow m_1 - a = a + m_1 \Rightarrow -a = +a.$$

Hence, $p \neq 3$. This argument, which is also valid for arbitrary odd order planes, was pointed out to the author by Rolando Pomareda. Now assume that π is a generalized Ott-Schaeffer plane of odd order q^2 , $q=p^r$. Each element of \mathcal{B} is Baer and for p>3, Foulser [4] has shown that the Baer subplanes involved must be disjoint. That is, since $|\mathcal{B}|=q$, \mathcal{B} must fix a 1-dimensional subspace

pointwise, which cannot be the case.

If p=3, it is possible that there are generalized Ott-Schaeffer planes of order 3^{2r} . However, hereafter, in this section, we shall consider only *even* order planes.

Theorem 2.2. Any tensor product plane π of even order q^2 is derivable. The derivable net is a regulus and the derived plane π is a tensor product plane defined by the inverse σ^{-1} of the automorphism σ used in the definition of π . Moreover, Fix $\sigma = GF(2)$ and the spread may be represented by x=0,

$$y = x \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}, \quad a \in K$$
$$y = x \begin{bmatrix} u & m(u, a) \\ a^{1-\sigma}, u+a \end{bmatrix}, m: K \times K \to K, \quad u, a \in K, a \neq 0.$$

Proof. Consider the notation of (2.1) with

$$\tau_a = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix}.$$

Then $y=0 \xrightarrow{\tau_a} y=x \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a & a^{\sigma+1} \\ 0 & a \end{bmatrix} = \begin{bmatrix} y=x \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix} \end{bmatrix}$. But, y=0, $y=x \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$ for $a \in K \simeq GF(q)$ is the vector form of a regulus in PG(3, K).

Now derive π using this "regulus" partial spread. Recall, if

$$(x_1, x_2, y_1, y_2) \xrightarrow{\tau_a} (x_1, x_1 a^{\sigma} + x_2, x_1 a + y_1, x_1 a^{\sigma+1} + x_2 a + y_1 a^{\sigma} + y_2)$$

represents τ_a in π by the standard representation of coordinates in $\overline{\pi}$ by (x_1, y_1, x_2, y_2) , we obtain:

$$(x_1, y_1, x_2, y_2) \xrightarrow{\overline{\tau}_a} (x_1, x_1 a + y_1, x_1 a^{\sigma} + x_2, x_1 a^{\sigma+1} + x_2 a + y_1 a^{\sigma} + y_2),$$

 $\bar{\tau}_a$ representing τ_a in $\bar{\pi}$ (see, e.g., Jha-Johnson [6]). Hence,

for b =

$$\begin{aligned} \overline{\tau}_{a} &= \begin{bmatrix} 1 & a & a^{\sigma} & a^{\sigma+1} \\ 0 & 1 & 0 & a^{\sigma} \\ 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & (a^{\sigma})^{\sigma^{-1}} \\ 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & b^{\sigma^{-1}} \\ 0 & 1 \end{bmatrix} \\ p &= a^{\sigma}. \quad \text{Hence, } \left\{ \tau_{a} &= \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \right\} \text{ in } \pi \text{ is } \left\{ \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & b^{\sigma^{-1}} \\ 0 & 1 \end{bmatrix} \right\} \text{ in } \overline{\pi}. \end{aligned}$$
We now consider the components $y = xM, M = \begin{bmatrix} m_{1} & m_{2} \\ m_{3} & m_{4} \end{bmatrix} \text{ of } \pi_{a} = \{(0, x_{2}, x_{2}a^{1-\sigma}, x_{3})\}$

 y_2 | $x_2, y_2 \in K$ }, $a \neq 0$ (Baer subplane of π). τ_a fixes

$$y = xM \Leftrightarrow \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} M = \begin{bmatrix} a & a^{\sigma+1} \\ 0 & a \end{bmatrix} + M \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix}$$
$$\Leftrightarrow \begin{bmatrix} a+m_1, & a^{\sigma+1}+m_1a^{\sigma}+m_2 \\ m_3 & , & a+m_3a^{\sigma}+m_4 \end{bmatrix} = \begin{bmatrix} m_1+m_3a^{\sigma}, & m_2+a^{\sigma}m_4 \\ m_3 & , & m_4 \end{bmatrix}$$
$$\Leftrightarrow m_3 = a^{1-\sigma},$$

and $a^{\sigma+1}+m_1a^{\sigma}=a^{\sigma}m_4$ or rather that $a+m_1=m_4$. Hence, $M=\begin{bmatrix} u & m(u,a)\\ a^{1-\sigma}, & u+a \end{bmatrix}$ for all u where m is a function from $K\times K$ to K. Note that if $[a^{1-\sigma}, u+a]$ does not take on all q^2 values then τ_a and τ_b for $a \neq b$ $(a, b \neq 0)$ fix the same component $y = xM \neq 0$ and hence $\langle \tau_1, \tau_2 \rangle$ must fix a 1-space pointwise on both y=xM and x=0. Hence, $\tau_a=\tau_b$. Thus, $[a^{1-\sigma}, u]=[c^{1-\sigma}, u] \Leftrightarrow$ $a=c \Leftrightarrow a^{1-\sigma}=c^{1-\sigma} \Leftrightarrow (ac^{-1})=(ac^{-1})^{\sigma} \Leftrightarrow \operatorname{Fix} \sigma=GF(2).$

Now we consider the general structure of a generalized Ott-Schaeffer plane Let \mathcal{G} be a collineation group of π of order q in the linear translation π. complement and such that each involution in π is Baer. By Johnson and Ostrom [8], \mathcal{G} is elementary abelian. Further, assume no two involutions in \mathcal{G} fix the same Baer subplane pointwise. Then

Lemma 2.3. The q-1 Baer subplanes corresponding to the involutions of \mathcal{G} lie across (q-1)q+1 components. The remaining q components are in an orbit under G.

Proof. \mathcal{G} fixes a component which we call $x=0, x=(x_1, x_2)$. If $g, h \in \mathcal{G}$ - $\langle 1 \rangle$ and Fix g and Fix h share a component $\mathcal{L} \neq (x=0)$ then $\langle g, h \rangle$ has fixed points on both \mathcal{L} and (x=0). Since \mathcal{Q} is linear, it follows that $\langle g, h \rangle$ is Baer—a contradiction. Hence, Fix g and Fix h cannot share a component $\pm (x=0)$. Thus, this accounts for q(q-1)+1 components. As the Baer subplanes corresponding to the involutions in \mathcal{G} do not intersect the remaining set Γ of q components, Γ must be a \mathcal{G} -orbit.

Now choose $(y=0) \in \Gamma$. Then

Lemma 2.4. We may choose a basis so that

$$\mathcal{G} = \left\{ \tau_{a} = \left| \begin{array}{c|c} 1 & a & f(a) & g(a) \\ 0 & 1 & 0 & f(a) \\ \hline & 1 & a \\ 0 & 1 \end{array} \right| a \in K \cong GF(q) \right\},\$$

f, g functions $K \rightarrow K$, where f is a 1-1 additive and g(a+b)=g(a)+g(b)+af(b)bf(a) for all $a, b \in K$.

and hence $b_1 = b_4$ ($d \neq 0$). We assert that $a_2 = c_2$,

$$\rho^{2} = \begin{bmatrix} I \begin{bmatrix} 1 & a_{2} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} b_{1} & b_{2} \\ 0 & b_{1} \end{bmatrix} + \begin{bmatrix} b_{1} & b_{2} \\ 0 & b_{1} \end{bmatrix} \begin{bmatrix} 1 & c_{2} \\ 0 & 1 \end{bmatrix} \\ 0 & I \end{bmatrix}$$

so $a_2 b_1 = b_1 c_2$.

If $b_1=0$ then ρ fixes π_0 pointwise. Hence, if $\rho \neq \tau$, $a_2=c_2$. Now there exists a component y=xT in the orbit of length q for $T=\begin{bmatrix} t_1 & t_2 \\ t_3 & t_4 \end{bmatrix}$. Change bases by $\begin{bmatrix} I & T \\ 0 & I \end{bmatrix}$. Then $x=0 \rightarrow x=0$,

$$y = 0 \leftrightarrow y = xT$$
$$y = x \rightarrow y = x(I+T).$$

(That is, after the basis change, y=x may not be an equation of a line.) Then $(1 \ a \ b_1 \ b_2)$

for
$$\rho = \begin{bmatrix} 0 & 1 & 0 & b_1 \\ 0 & 1 & a \\ 0 & 0 & 1 \end{bmatrix}$$
 we obtain
$$\begin{bmatrix} I & T \\ 0 & I \end{bmatrix} \rho \begin{bmatrix} I & T \\ 0 & I \end{bmatrix} = \begin{pmatrix} 1 & a & (b_1 + at_3), & b_2 + a(t_1 + t_4) \\ 0 & 1 & 0 & (b_1 + at_3) \\ 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Letting

$$f(a) = b_1 + at_3$$
$$g(a) = b_2 + a(t_1 + t_4)$$

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 $(\text{note}\begin{pmatrix} 1 & a & c_1 & c_2 \\ 0 & 1 & 0 & c_1 \\ 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ and} \begin{pmatrix} 1 & a & \overline{c_1} & \overline{c_2} \\ 0 & 1 & 0 & \overline{c_1} \\ 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 \end{pmatrix} \in \mathcal{Q} \text{ implies } c_1 = \overline{c_1}, c_2 = \overline{c_2} \text{ since there are no ela-}$

tions in \mathcal{G}) where $f, g: K \rightarrow K$, we have the proof to (2.4) since \mathcal{G} is elementary abelian. Note

$$y = 0 \xrightarrow{\mathcal{Q}} y = x \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \begin{bmatrix} f(a) & g(a) \\ 0 & f(a) \end{bmatrix}$$
$$\equiv y = x \begin{bmatrix} f(a), & g(a) + af(a) \\ 0, & f(a) \end{bmatrix}.$$

If f(a)=0 for $a \neq 0$, then $y = x \begin{bmatrix} 0 & g(a) \\ 0 & 0 \end{bmatrix} = \{(x_1, x_2, 0, x_1 g(a)) | x_1, x_2 \in K\} \cap \{(x_1, x_2, 0, 0) | x_1, x_2 \in K\}$ is $\{(0, x_2, 0, 0) | x_2 \in K\}$ and since both equations represent components, we have a

 $\{(0, x_2, 0, 0) | x_2 \in K\}$ and since both equations represent components, we have a contradiction. $\therefore f$ is 1-1. And, we have:

Lemma 2.5. The \mathcal{Q} -orbit of length q may be represented by $y=x\begin{bmatrix} f(a)\\ 0\\ f(a)\end{bmatrix}$ f(a) where $a \in K$.

At this point, let the components be $x=0, y=0, y=xM, M \in \mathcal{M}$ but I may not be in \mathcal{M} . Let $\tau_a = \begin{pmatrix} 1 & a & f(a) & g(a) \\ 0 & 1 & 0 & f(a) \\ 1 & a & a \\ 0 & 1 & a \end{pmatrix}$ for $a \neq 0$.

(2.6).
$$\tau_a \text{ fixes } y = xM \Leftrightarrow M = \begin{bmatrix} m_1 & m_2 \\ m_3 & m_4 \end{bmatrix}, m_3 = a^{-1}f(a), m_4 = m_1 + a^{-1}g(a).$$

Proof.
$$(x, xM) \xrightarrow{\tau_a} \left(x \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}, x \left(\begin{bmatrix} f(a) & g(a) \\ 0 & f(a) \end{bmatrix} + M \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \right) \right) \in y = xM \Leftrightarrow \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}$$
$$M = \begin{bmatrix} f(a) & g(a) \\ 0 & f(a) \end{bmatrix} + M \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}.$$

Hence we have the following set of components

$$y = x \begin{bmatrix} u & m(u, a) \\ a^{-1}f(a), & u + a^{-1}g(a) \end{bmatrix}$$

for all $a \neq 0$, $u \in K$, $m: K \times K \rightarrow K$,

$$x = 0$$

$$y = x \begin{bmatrix} u & h(u) \\ 0 & u \end{bmatrix}$$

where $h(u) = g(f^{-1}(u)) + uf^{-1}(u)$ for all $u \in K$. So, we obtain the following theorem,

Theorem 2.7. Let π be a generalized Ott-Schaeffer plane of even order q^2 , kernel $K \cong GF(q)$. Let \mathcal{G} be a collineation group of order q in the linear translation complement such that each involution of \mathcal{G} is Baer and no two involutions fix the same Baer subplane pointwise. Then π and \mathcal{G} may be represented in the following form:

$$\mathcal{G} = \left\{ \tau_a = \begin{pmatrix} 1 & a & f(a), & g(a) \\ 0 & 1 & 0 & f(a) \\ 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 \end{pmatrix} \middle| a \in K, f \ 1 - 1 \text{ and additive} \\ g(a+b) = g(a) + g(b) + bf(a) + af(b) \right\}.$$

The components for π are x=0, y=0, $y=x\begin{bmatrix} u & h(u) \\ 0 & u \end{bmatrix} \forall u \in K$, $h(u)=uf^{-1}(u)+g(f^{-1}(u))$, h(0)=0, and $y=x\begin{bmatrix} u & m(u,a) \\ a^{-1}f(a), & u+a^{-1}g(a) \end{bmatrix}$ for some function $m: K \times K \to K$.

Proof. Note y = x may not represent a component.

3. Groups of order q(q-1)

We first assume that π is a tensor product plane of even order q^2 that admits a group \mathcal{GH} of order q(q-1). Further, we assume $\mathcal{G} = \left\{ \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \middle| a \in K \equiv GF(q) \right\}$ as in section 2 and $\mathcal{H} = \left\{ \begin{bmatrix} a \\ a^{-1} \end{bmatrix} \otimes \begin{bmatrix} a \\ a^{-\sigma} \end{bmatrix} \middle| a \in K \right\}$ for some $\sigma \in \operatorname{Aut} K$. Recall from (2.2) that a spread for π may be represented in the form x=0, $y=x\begin{bmatrix} u \\ a^{1-\sigma}, & u+a \end{bmatrix}$ for all $u, a \in K, m$ a function from $K \times K \to K$. Let $\tau_a = \begin{pmatrix} 1 & a^{\sigma} & a & a^{\sigma+1} \\ 0 & 1 & 0 & a \\ 0 & 0 & 1 & a^{\sigma} \\ 0 & 0 & 0 & 1 \end{pmatrix}$ and $\rho_a = \begin{bmatrix} a & 0 \\ 0 & a^{-1} \end{bmatrix} \otimes \begin{bmatrix} a^{\sigma} & 0 \\ 0 & a^{-\sigma} \end{bmatrix} = \begin{pmatrix} a^{\sigma+1} & 0 & 0 & 0 \\ 0 & a^{1-\sigma} & 0 & 0 \\ 0 & 0 & a^{\sigma-1} & 0 \\ 0 & 0 & 0 & a^{-\sigma-1} \end{bmatrix}$.

Consider the images of

$$y = x \begin{bmatrix} u , m(u, b) \\ b^{1-\sigma}, u+b \end{bmatrix}$$
$$\xrightarrow{\tau_a} \begin{bmatrix} x \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix}, x \begin{bmatrix} a & a^{\sigma+1} \\ 0 & a \end{bmatrix} + \begin{bmatrix} u , m(u, b) \\ b^{1-\sigma}, u+b \end{bmatrix} \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \end{bmatrix}$$

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$$\begin{split} & \in y = x \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} a+u, & a^{\sigma+1}+ua^{\sigma}+m(u,b) \\ b^{1-\sigma}, & a+b^{1-\sigma}a^{\sigma}+u+b \end{bmatrix} \\ & = \begin{bmatrix} y = x \begin{bmatrix} (a+u+a^{\sigma}b^{1-\sigma}), & m(u,b)+a^{\sigma}(b^{1-\sigma}a^{\sigma}+b) \\ b^{1-\sigma}, & (a+u+a^{\sigma}b^{1-\sigma})+b \end{bmatrix} \end{bmatrix}. \end{split}$$

So,

Lemma 3.1.

$$m(a+u+a^{\sigma}b^{1-\sigma},b)=m(u,b)+a^{\sigma}(b^{1-\sigma}a^{\sigma}+b) \text{ for all } a,u,b,b\neq 0 \text{ of } K.$$

Applying ρ_a we obtain

Lemma 3.2.

$$y = x \begin{bmatrix} u & m(u, b) \\ b^{1-\sigma}, & u+b \end{bmatrix}$$

$$\stackrel{\rho_{a}}{\to} y = x \begin{bmatrix} a^{-(\sigma+1)} & \\ a^{-(1-\sigma)} \end{bmatrix} \begin{bmatrix} u & m(u, b) \\ b^{1-\sigma}, & u+b \end{bmatrix} \begin{bmatrix} a^{\sigma-1} & 0 \\ 0 & a^{-\sigma-1} \end{bmatrix}$$

$$= \begin{bmatrix} y = x \begin{bmatrix} ua^{-2}, & m(u, b)a^{-2(\sigma+1)} \\ (ba^{-2})^{1-\sigma}, & ua^{-2} + ba^{-2} \end{bmatrix}].$$

So, $m(ua^{-2}, ba^{-2}) = m(u, b)a^{-2(\sigma+1)}$ for all u, a, b in $K, a \neq 0, b \neq 0$.

Hence,

Lemma 3.3.

 $y=x\begin{bmatrix} b, m(b, b)\\ b^{1-\sigma}, 0\end{bmatrix}$ has $\frac{q(q-1)}{2}$ images under GH and this orbit includes all components with a zero in the (2, 2)-entry of the image matrix.

In particular, we have the orbits of length $q\left(\frac{q-1}{2}\right)$ defined by the images of $y = x \begin{bmatrix} 1, & m(1, 1) \\ 1, & 0 \end{bmatrix}$ and $y = x \begin{bmatrix} 0, & m(0, 1) \\ 1, & 1 \end{bmatrix}$ (by analogy). By (3.1) and (3.2), the orbit of $y = x \begin{bmatrix} 1, & m(1, 1) = m_1 \\ 1, & 0 \end{bmatrix}$ is:

$$y = x \begin{bmatrix} 1 & m_1 \\ 1 & 0 \end{bmatrix}^{\frac{\tau_a}{2}} y = x \begin{bmatrix} a+1+a^{\sigma}, & m_1+a^{\sigma}(a^{\sigma}+1) \\ 1 & , & a+a^{\sigma} \end{bmatrix}$$

$$\stackrel{\rho_b}{\rightarrow} y = x \begin{bmatrix} (a+1+a^{\sigma}) b^{-2}, & (m_1+a^{\sigma}(a^{\sigma}+1)) b^{-2(\sigma+1)} \\ (b^{-2})^{1-\sigma} & , & (a+1+a^{\sigma}) b^{-2} + b^{-2} \end{bmatrix}$$

$$\equiv \begin{bmatrix} y = x \begin{bmatrix} (a+1+a^{\sigma}) c, & (m_1+a^{\sigma}(a^{\sigma}+1)) c^{1+\sigma} \\ c^{1-\sigma} & , & (a+a^{\sigma}) c \end{bmatrix} \end{bmatrix}$$

for all $a, c \neq 0$ in K.

Similarly, the orbit of $\begin{bmatrix} 0, & m(0, 1) = m_0 \\ 1, & 1 \end{bmatrix}$ is

$$\left\{y = x \begin{bmatrix} (a+a^{\sigma}) c, & (m_0+a^{\sigma}(a^{\sigma}+1)) c^{\sigma+1} \\ c^{1-\sigma}, & (a+a^{\sigma}+1) c \end{bmatrix}\right\}.$$

Therefore, we obtain the following theorem:

Theorem 3.4. A translation plane π of even order q^2 and kernel $k \cong GF(q)$ admits the group $H = \left\{ \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix} | a \in K \right\}$. $\left\{ \begin{bmatrix} a \\ a^{-1} \end{bmatrix} \otimes \begin{bmatrix} a^{\sigma} \\ a^{-\sigma} \end{bmatrix} | a \in K - \{0\} \right\}$ with components x = 0, y = 0, $y = x \Leftrightarrow$ there exists constants m_0 , $m_1 \in K$ such that the spread for π may be represented by the matrix spread set:

$$x = 0, y = x \begin{bmatrix} u & 0 \\ 0 & u \end{bmatrix},$$

$$y = x \begin{bmatrix} (a^{\sigma} + a + 1) c, (m_1 + a^{\sigma}(a^{\sigma} + 1)) c^{\sigma + 1} \\ c^{1 - \sigma}, (a + a^{\sigma}) c \end{bmatrix},$$

$$y = x \begin{bmatrix} (a^{\sigma} + a) c, (m_0 + a^{\sigma}(a^{\sigma} + 1)) c^{\sigma + 1} \\ c^{1 - \sigma}, (a + a^{\sigma} + 1) c \end{bmatrix}$$

for all u, a, $c \in K$, $c \neq 0$. Also, the fixed field of $\sigma = GF(2)$, $q = 2^r$, and r is odd.

Proof. It remains to prove that r is odd. We see that $\begin{bmatrix} 0 & m_0 \\ 1 & 1 \end{bmatrix}$ and $\begin{bmatrix} 1 & m_1 \\ 1 & 1 \end{bmatrix}$ are in distinct *H*-orbits. Hence $\begin{bmatrix} 0 & m_1 \\ 1 & 1 \end{bmatrix} \xrightarrow{\tau_a} \begin{bmatrix} a+a^{\sigma}, & m_0+a^{\sigma}(a^{\sigma}+1) \\ 1 & , & a+a^{\sigma}+1 \end{bmatrix}$, so that $a+a^{\sigma} \neq 1$. Suppose $b^2 = b+1$ for some $b \in K$. Then if $q=2^r$, assume r even, and $\sigma = 2^s$ for s odd. Then $(b^2)^{\sigma/2} = b^{\sigma/2} + 1 = b + 1 \Leftrightarrow b^{\sigma/2} = b \Leftrightarrow b^{\sigma} = b^2 \Leftrightarrow b^{\sigma-2} = 1 \Leftrightarrow (\text{for } b \neq 1), \begin{bmatrix} \sigma-2 \\ 2 \\ 2 \end{bmatrix}, 2^r - 1 \end{bmatrix} \neq 1$. Since $\frac{\sigma-2}{2} = 2^{s-1} - 1$ and $(s-1, r) = 2 \cdot t$, we have that GF(4) cannot be a subfield of GF(q). That is, r is odd.

NOTES 3.5. In the Ott-Schaeffer planes $m_0 = m_1 = 1$. Here, at least it is possible that there are other translation planes distinct from the O-S planes and admitting the same group of order q(q-1) that the O-S planes admit.

We now further consider generalized Ott-Schaeffer planes π of order q^2 and kernel $K \cong GF(q)$. We may use the representation given in (2.7). Assume there is a linear collineation group H such that $HK^*/K^* \cong H(K^* = K - \{0\})$ and |H| = q(q-1). Note that we use the notation HK^* to refer to the product of H by the kernel homology group of order q-1.

Lemma 3.6. A Sylow 2-subgroup $S_2 \leq H$ or π is Ott-Schaeffer.

Proof. Let S_2 fix the component \mathcal{L} . Since the involutions of H (see (2.7)) are all Baer, it follows from Johnson-Ostrom [8] (3.27) that if π is not Ott-Schaeffer then the group R generated by the Sylow 2-subgroups of H is reducible and solvable and by the argument to [8] (3.27), R must be a 2-group. That is, $S_2 \leq H$.

Lemma 3.7. $H = S_2 \cdot C$ where C is a 2-complement of S_2 . Then C fixes two components.

Proof. Clearly, S_2 is a Hall normal subgroup so let C be a 2-complement of order q-1.

C fixes \mathcal{L} and by Maschke's Theorem, decompose $\pi = \mathcal{L} \oplus \mathcal{W}$ where \mathcal{W} is a C-invariant 2-space. Either \mathcal{W} is a component and (3.7) is finished or \mathcal{W} is a C-invariant Baer subplane. Further, \mathcal{W} is Desarguesian and $C | \mathcal{W} \leq GL(2, q)$ acting on \mathcal{W} . Hence, C must fix two components of \mathcal{W} which are 1-spaces of π . Hence, C fixes the components of π which contain the C-invariant components of \mathcal{W} .

Lemma 3.8. H acts faithfully on \mathcal{L} .

Proof. If $h \in H$ fixes \mathcal{L} pointwise then h is a homology and by the orbit structure of π (see section 2), it must be that the coaxis of h is moved by S_2 . That is, there must be elations in H by André [1]. Hence, we have the proof to (3.8).

Lemma 3.9. C acts regularly on $S_2 - \langle 1 \rangle$ by conjugation.

Proof. Represent S_2 as in (2.7), then let

$$h = \left[\begin{array}{c|c} A & B \\ \hline 0 & C \end{array} \right] \in \mathcal{C}.$$

So $A, C \in N_{GL(2,q)} \left[\left\{ \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \middle| a \in K \right\} \right]$ so that

$$A = \begin{bmatrix} a_1 & a_2 \\ 0 & a_4 \end{bmatrix}, \quad C = \begin{bmatrix} c_1 & c_2 \\ 0 & c_4 \end{bmatrix}.$$

Let $B = \begin{bmatrix} b_1 & b_2 \\ b_3 & b_4 \end{bmatrix}$. If $\tau_a^h = \tau_a$ for some $a \neq 0$ (see (2.7)) then clearly $a_1 = a_4, c_1 = c_4$ and so $\tau_b^h = \tau_b \forall b \neq 0$. This implies

$$[A+C]\begin{bmatrix} f(b) & g(b) \\ 0 & f(b) \end{bmatrix} = B\begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} B = \begin{bmatrix} bb_3, & b(b_1+b_4) \\ 0, & bb_3 \end{bmatrix}$$

for all $b \neq 0$.

Hence

$$\begin{bmatrix} a_1+c_1, & a_2+c_2 \\ 0, & a_4+c_4 \end{bmatrix} \begin{bmatrix} f(b) & g(b) \\ 0 & f(b) \end{bmatrix} = \begin{bmatrix} bb_3 & b(b_1+b_4) \\ 0 & bb_3 \end{bmatrix}.$$

So $(a_2+c_2)f(b)+(a_1+c_1)g(b)=b(b_1+b_4)$. That is, if $a_1 \neq c_1$ then $g(b)=bK_1+f(b)K_2$ for

$$K_1 = \begin{bmatrix} b_1 + b_4 \\ a_1 + c_1 \end{bmatrix}$$
 and $K_2 = \begin{bmatrix} a_2 + c_2 \\ a_1 + c_1 \end{bmatrix}$.

Thus, if $a_1 \neq c_1$ then g is additive.

However, g(b+t)=g(b)+g(t)+bf(t)+tf(b) so that bf(t)=tf(b) for all $b, t \in K$. Hence f(t)=tf(1).

But the components include the q(q-1) elements

$$y = x \begin{bmatrix} u & m(u, a) \\ a^{-1}f(a), & u + a^{-1}g(a) \end{bmatrix}$$
 for $u, a \in K, a \neq 0$

(see (2.7)) so that the (2, 1)-entries are always $a^{-1}af(1)=f(1)$. That is,

$$y = x \begin{bmatrix} u, & m(u, a) \\ f(1), & u + a^{-1}g(a) \end{bmatrix}$$

for f(1) a constant, represents q(q-1) components which clearly is a contradiction

Hence, $a_1+c_1=0$ so that $a_1=a_4=c_1=c_4$ and we have

$$(a_2+c_2f(b))=b(b_1+b_4).$$

If $a_2+c_2 \neq 0$ then $f(b)=b \cdot a$ for a some constant. Then we still have $y=x\begin{bmatrix} u & , & m(u,a) \\ f(1), & u+a^{-1}g(a) \end{bmatrix}$ to represent q(q-1) components—a contradiction. Thus, $a_2=c_2$ and $b_1=b_4$. So the element in C has the form $\begin{pmatrix} a_1 & a_2 & b_1 & b_2 \\ 0 & a_1 & 0 & b_1 \\ 0 & 0 & a_1 & a_2 \\ 0 & 0 & 0 & a_1 \end{pmatrix}$. Multiplying by $a_1^{-1} I_4$ we obtain $\rho = \begin{pmatrix} 1 & a_2a_1^{-1} & b_1a_1^{-1} & b_2a_1^{-1} \\ 0 & 1 & 0 & b_1a_1^{-1} \\ 0 & 0 & 1 & a_2a_1^{-1} \\ 0 & 0 & 0 & 1 \end{pmatrix}$. Let $a_2a_1^{-1}=e$. We have $\tau_e \in S_2$, $\tau_e = \begin{pmatrix} 1 & e & f(e) & g(e) \\ 0 & 1 & 0 & f(e) \\ 0 & 0 & 1 & e \\ 0 & 0 & 0 & 1 \end{pmatrix}$. Since $S_2 \leq HK^*$ we must have

that $\rho = \tau_e$. In other words, the element is in $\mathcal{S}_2 K^*$. However, we assumed that $HK^*/K^* \simeq H$. This proves (3.9).

Thus, \mathcal{C} must fix one of the components in the orbit of \mathcal{S}_2 of length q. That is, \mathcal{C} must fix a component of the form $y = x \begin{bmatrix} u & h(u) \\ 0 & u \end{bmatrix}$ for some $u \in K$.

So, we may choose a 2-complement C for S_z so that C fixes y=0.

(3.10). Thus, the elements of C have the form

$$\left(\begin{array}{c} \begin{bmatrix} a_1 & a_3 \\ 0 & a_4 \end{bmatrix} \\ \hline \\ 0 \\ \hline \begin{bmatrix} c_1 & c_2 \\ 0 & c_4 \end{bmatrix} \\ \vdots \\ \begin{bmatrix} x, x \begin{bmatrix} u & h(u) \\ 0 & u \end{bmatrix} \end{bmatrix} \rightarrow \begin{bmatrix} x \begin{bmatrix} a_1 & a_2 \\ 0 & a_4 \end{bmatrix}, x \begin{bmatrix} u & h(u) \\ 0 & u \end{bmatrix} \begin{bmatrix} c_1 & c_2 \\ 0 & c_4 \end{bmatrix} \end{bmatrix}$$

so that

$$\begin{bmatrix} a_1^{-1}, \ a_2a_1^{-1}a_4^{-1} \\ 0, \ a_4^{-1} \end{bmatrix} \begin{bmatrix} u \ h(u) \\ 0 \ u \end{bmatrix} \begin{bmatrix} c_1 \ c_2 \\ 0 \ c_4 \end{bmatrix}$$

=
$$\begin{bmatrix} ua_1^{-1}, \ a_1^{-1}h(u) + a_2a_1^{-1}a_4^{-1}u \\ 0, \ ua_4^{-1} \end{bmatrix} \begin{bmatrix} c_1 \ c_2 \\ 0 \ c_4 \end{bmatrix}$$

=
$$\begin{bmatrix} ua_1^{-1}c_1, \ ua_1^{-1}c_2 + (a_1^{-1}h(u) + a_2a_1^{-1}a_4^{-1}u) \ c_4 \\ 0, \ ua_4^{-1}c_4 \end{bmatrix} \in \left\{ \begin{bmatrix} u \ f(u) \\ 0 \ u \end{bmatrix} \middle| \ u \in K \right\}.$$

(3.11). So
$$a_1^{-1}c_1 = a_4^{-1}c_4$$
.
Since $HK^*/K^* \cong H$, then $CK^*/K^* \cong C \Leftrightarrow C \cap K^* = \{1\}$. So multiplying a typical element by $\begin{bmatrix} a_1^{-1} & & \\ & a_1^{-1} & \\ & & a_1^{-1} \end{bmatrix}$ then in CK^* , there are $q-1$ elements of the general form $\begin{bmatrix} 1 & a_2 \\ & 0 & a_4 \\ & & c & c_2 \\ & 0 & a_4c \end{bmatrix}$. Assume two such elements have equal (2,2)-entries.

Consider

$$\rho = \begin{bmatrix} 1 & a_2 & & \\ 0 & a_4 & & \\ & \overline{c} & \overline{c}_2 \\ & 0 & a_4 \overline{c} \end{bmatrix} \text{ and } \chi = \begin{bmatrix} 1 & a_2 & & \\ 0 & a_4 & & \\ & c & c_2 \\ & 0 & a_4 c \end{bmatrix}$$

when $a_4 = a_4$. Then the product

$$\rho \boldsymbol{\chi}^{-1} = \left(\begin{array}{c} \begin{bmatrix} 1 & d \\ 0 & 1 \end{bmatrix} \\ \hline \end{array} \right)$$

where $d = \bar{a}_2 a_4^{-1} + a_2 a_4^{-1}$ and $(\rho \chi^{-1})^2$ must fix x = 0 pointwise. By (3.8), $(\rho \chi^{-1})^2 =$

1. However,
$$|CK^*||(q-1)^2$$
, so $\rho \chi^{-1} = 1 \Leftrightarrow \rho = \chi$. Thus, there must exist a collineation $\rho = \begin{bmatrix} 1 & a_2 \\ 0 & a \\ & c & c_2 \\ & 0 & ac \end{bmatrix}$ where $|a| = q - 1$.

Hence, since $S_2 \trianglelefteq HK^*$, we obtain

$$\begin{bmatrix} A^{-1} \\ C^{-1} \end{bmatrix} \begin{bmatrix} 1 & b & f(b) & g(b) \\ 0 & 1 & 0 & f(b) \\ 1 & b \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A \\ C \end{bmatrix}$$
$$= \begin{bmatrix} A^{-1} \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} A & A^{-1} \begin{bmatrix} f(b) & g(b) \\ 0 & f(b) \end{bmatrix} C \\ 0 & C^{-1} \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} C \end{bmatrix} \in S_2$$

where $A = \begin{bmatrix} 1 & a_2 \\ 0 & a \end{bmatrix}$, $C = \begin{bmatrix} c & c_2 \\ 0 & ac \end{bmatrix}$ so that

$$A^{-1} \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} A = \begin{bmatrix} 1 & a_2 a^{-1} \\ 0 & a^{-1} \end{bmatrix} \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a_2 \\ 0 & a \end{bmatrix} = \begin{bmatrix} 1, & ba \\ 0, & 1 \end{bmatrix} = C^{-1} \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} C$$

and

$$A^{-1} \begin{bmatrix} f(b) \ g(b) \\ 0 \ f(b) \end{bmatrix} C = \begin{bmatrix} 1 \ a_2 a^{-1} \\ 0 \ a^{-1} \end{bmatrix} \begin{bmatrix} f(b) \ g(b) \\ 0 \ f(b) \end{bmatrix} \begin{bmatrix} c \ c_2 \\ 0 \ ac \end{bmatrix}$$
$$= \begin{bmatrix} cf(b), \ f(b) \ (c_2 + a_2 c) + g(b) \ ac \\ 0 \ , \ cf(b) \end{bmatrix}.$$

Since |a|=q-1, $\exists j \ni a^{j}=c$, so that we obtain the elements

$$\begin{bmatrix} 1, \ ab \ a^{j}f(b), \ f(b)(c_{2}+a_{2}a^{j})+g(b)a^{j+1}\\ 0, \ 1 & 0, \qquad a^{j}f(b)\\ 1 & ab\\ 0 & 1 \end{bmatrix}$$

in S_2 . Hence,

(3.12) $f(ab) = a^{j} f(b)$ for all *b* in *K** and

(3.13)
$$g(ab) = f(b)(c_2 + a_2a^j) + g(b)a^{j+1}$$
 for all b in K^* .

Also,

$$\rho^{i} = \begin{pmatrix} 1 & a_{2} \left[\frac{a^{i} - 1}{a - 1} \right] \\ 0 & a^{i} \\ \hline & \\ a^{ij} & c_{2} a^{(i-1)j} \left[\frac{a^{i} - 1}{a - 1} \right] \\ & a^{i(j+1)} \end{pmatrix}.$$

The previous argument applied to ρ^i implies

(3.14)
$$f(a^{i}b) = a^{ij}f(b)$$
 for all b in K^* and
(3.15) $g(a^{i}b) = f(b) (c_2 a^{(i-1)j} \left[\frac{a^{i}-1}{a-1}\right] + a_2 a^{ij} \left[\frac{a^{i}-1}{a-1}\right] + g(b) a^{i(j+1)}$
for all $i \ge 1, b$ in K .

Let b=1 in (3.14) and $a^i=c$ to obtain $f(c)=c^j f(1)$ and further (3.16) $f(c)=c^{\tau}f$ where $c^j=c^{\tau}$ and $\tau \in \operatorname{Aut} K, f=f(1)$.

Pf. f is additive and i is arbitrary as |a|=q-1. From (3.10),

$$y = x \begin{bmatrix} f(b), bf(b) + g(b) \\ 0, f(b) \end{bmatrix}$$

$$\stackrel{\rho}{\to} y = x \begin{bmatrix} f(b)a^{\tau}, \{f(b) (c_2 + a_2a^{\tau}) + f(b) ba^{\tau+1} + g(b) a^{\tau+1} \} \\ 0, f(b) a^{\tau} \end{bmatrix}.$$

Using (3.16), $f(b)a^{\tau} = f(ab)$ so that the (2,2) entry of the preceding matrix is df(d)+g(d) for d=ab since $(ab)f(ab)=f(b)ba^{\tau+1}$, we obtain

(3.17)
$$g(ab) = g(b) a^{\tau+1} + b^{\tau} f(1) (c_2 + a_2 a^{\tau})$$
 for all b in K*.

Let b=1 in (3.15) to obtain:

(3.18)
$$g(a^i) = g(1) a^{i(\tau+1)} + f(1) (c_2 + a_2 a^{\tau}) \left[a^{(i-1)\tau} \left[\frac{a^i - 1}{a - 1} \right] \right]$$
 all $i \ge 1$ in Z.

Since |a| = q - 1, we obtain

$$g(c) = g(1) c^{\tau+1} + f(1) \frac{(c_2 + a_2 a^{\tau})}{(a-1)} a^{-\tau} (c^{\tau}(c-1))$$

for all $c \neq 0$. Let $s = f(1) \frac{(c_2 + a_2 a^7)}{(a-1)} a^{-\tau}$, g(1) = g, f(1) = f to obtain (3.19) $g(c) = c^{\tau+1}(s+g) + c^{\tau} s$

for all $c \neq 0$ in K.

Recall $f(d) = d^{\tau} f$ for all d and g(e+d) = g(e) + g(d) + ef(d) + df(e) for all e, d in K. Thus,

$$g(e+d) = (e+d)^{\tau+1}(s+g) + (e+d)^{\tau} s$$

= $(e^{\tau+1}(s+g) + e^{\tau} s) + (d^{\tau+1}(s+g) + d^{\tau} s) + ed^{\tau} f + de^{\tau} f$

so that

$$(3.20) \quad (ed^{\tau} + ed^{\tau}) (s + g + f) = 0$$

so that either $\tau=1$ or s+g+f=0. If $\tau=1$ then from (2.7), the components have the form

$$\begin{bmatrix} y = x \begin{bmatrix} u & h(u) \\ 0 & u \end{bmatrix} \end{bmatrix}, \begin{bmatrix} y = x \begin{bmatrix} u & m(u, d) \\ d^{-1}f(d), & u + d^{-1}g(d) \end{bmatrix}$$
$$\equiv \begin{bmatrix} y = x \begin{bmatrix} u, & m(u, d) \\ f, & u + d^{-1}g(d) \end{bmatrix},$$

But, the latter set for all $u, d \neq 0$ represents q(q-1) components. For $d_1 \neq d_2$

$$\begin{bmatrix} u, & m(u, d_1) \\ f, & u+d^{-1}g(d_1) \end{bmatrix} - \begin{bmatrix} u, & m(u, d_2) \\ f, & u+d^{-1}g(d_2) \end{bmatrix}$$

is singular so $\tau \equiv 1$.

Change bases by

$$\chi = \left(\begin{array}{c|c} 1 & t \\ 0 & 1 \\ \hline 0 & 1 \\ \hline 0 & 1 \\ 0 & 1 \end{array} \right)$$

where $t = \frac{a_2}{1+a}$. Recall

$$\tau_{d} = \begin{pmatrix} 1 & d & f(d) & g(d) \\ 0 & 1 & 0 & f(d) \\ 0 & 1 & d \\ 0 & 0 & 1 \end{pmatrix}$$

(from section 2) and χ commutes with τ_d . Recall

$$\rho = \left(\begin{array}{c|c} 1 & a_2 \\ 0 & 1 \\ \hline \\ a^{\mathsf{T}} & c_2 \\ 0 & a^{\mathsf{T}+1} \end{array} \right)$$

so that

$$\bar{p} = \chi \rho \chi^{-1} = \left(\frac{\begin{array}{c} 1 & 0 \\ 0 & a \\ \end{array}}{0} \middle| \begin{array}{c} a^{\tau} & \frac{a^{\tau}(a+1) s}{f} \\ 0 & a^{\tau+1} \end{array} \right)$$

as

$$\begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a_2 \\ 0 & a \end{bmatrix} \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & t + a_2 + ta \\ 0 & a \end{bmatrix}$$

when $t = \frac{a_2}{1+a}$ so that $t + a_2 + ta = \frac{a_2}{1+a} + a_2 + \frac{a_2}{1+a} a = 0$ and
 $\begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a^{\mathsf{T}} & c_2 \\ 0 & a^{\mathsf{T}+1} \end{bmatrix} \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a^{\mathsf{T}} & a^{\mathsf{T}} t + c_2 + ta^{\mathsf{T}+1} \\ 0 & a^{\mathsf{T}+1} \end{bmatrix}$

where

$$a^{\tau} t + c_2 + ta^{\tau+1} = a^{\tau} \frac{a_2}{1+a} + \frac{a^{\tau}(a+1)}{f} s + a_2 a^{\tau} + \frac{a_2}{1+a} a^{\tau+1} = \frac{a^{\tau}(a+1)s}{f}$$

as

$$s = f \frac{(c_2 + a_2 a^{\tau}) a^{-\tau}}{(1+a)}.$$

We originally had the components in the form

$$y = x \begin{bmatrix} f(b) & g(b) + bf(b) \\ 0 & f(b) \end{bmatrix}$$

and

$$y = x \begin{bmatrix} u & m(u, c) \\ c^{-1}f(c), & u+c^{-1}g(c) \end{bmatrix}.$$

Apply χ , the forms become:

$$y = x \begin{bmatrix} f(b) & g(b) + bf(b) \\ 0 & f(b) \end{bmatrix}$$

and

$$\begin{bmatrix} y = x \begin{bmatrix} u + c^{\tau-1} f \cdot t, & - \\ c^{\tau-1} f & u + c^{\tau-1} f \cdot t + c^{-1} g(c) \end{bmatrix}$$
$$\equiv \begin{bmatrix} y = x \begin{bmatrix} v & , & - \\ c^{\tau-1} f, & v + c^{-1} g(c) \end{bmatrix} \end{bmatrix}$$

for $v = u + c^{\tau-1} f \cdot t$. In other words the form is invariant under χ .

Now $g(b)+bf(b)=(b^{\tau+1}(s+g)+b^{\tau}s+b^{\tau+1}f)$ by (3.19). By (3.20) s+g+f=0 so that $g(b)+bf(b)=b^{\tau}s$.

Change bases by

$$\gamma = \begin{bmatrix} I & 0 \\ 0 \begin{bmatrix} f^{-1} & sf^{-2} \\ 0 & f^{-1} \end{bmatrix}$$

so that

$$y = x \begin{bmatrix} b^{\tau} f, & b^{\tau} s \\ 0, & b^{\tau} f \end{bmatrix} \xrightarrow{\gamma} y = x \begin{bmatrix} b^{\tau} & 0 \\ 0 & b^{\tau} \end{bmatrix},$$
$$\begin{bmatrix} y = x \begin{bmatrix} v, & & \\ c^{\tau-1} f, & v+c^{-1} g(c) \end{bmatrix} = \begin{bmatrix} y = x \begin{bmatrix} v, & & \\ c^{\tau-1} f, & v+c^{\tau}(s+g)+c^{\tau-1} s \end{bmatrix} \begin{bmatrix} y \\ \rightarrow y = x \begin{bmatrix} v f^{-1}, & \\ c^{\tau-1} f, & v f^{-1}+c^{\tau} \end{bmatrix}$$

since s+g+f=0.

Furthermore,

$$\gamma^{-1}\bar{\rho}\gamma = \begin{pmatrix} 1 & 0 \\ 0 & a \\ \\ & \\ & \\ \end{bmatrix} \begin{bmatrix} 1 & sf^{-1} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a^{\tau}, & a^{\tau}(a+1)\frac{s}{f} \\ 0, & a^{\tau+1} \end{bmatrix} \begin{bmatrix} 1 & sf^{-1} \\ 0 & 1 \end{bmatrix} \\ = \begin{pmatrix} 1 & 0 \\ 0 & a \\ \\ & \\ & \\ & \\ & \\ \end{bmatrix} \begin{pmatrix} a^{\tau} & 0 \\ 0 & a^{\tau+1} \\ \end{pmatrix}$$

and

$$\gamma^{-1} \tau_{d} \gamma = \left(\frac{1}{0} \frac{d}{1} \right) \left| \frac{ \begin{bmatrix} f(d) \ g(d) \\ 0 \ f(d) \end{bmatrix} \begin{bmatrix} f^{-1}, \ sf^{-2} \\ 0, \ f^{-1} \end{bmatrix}}{1 \ d} \right| \frac{1}{0} \frac{d}{1} \frac{d}{$$

and

$$\begin{bmatrix} f(d) & g(d) \\ 0 & f(d) \end{bmatrix} \begin{bmatrix} f^{-1} & sf^{-2} \\ 0 & f^{-1} \end{bmatrix} = \begin{bmatrix} d^{\tau}f & d^{\tau+1}(s+g) + d^{\tau}s \\ 0 & d^{\tau}f \end{bmatrix} \begin{bmatrix} f^{-1} & sf^{-2} \\ 0 & f^{-1} \end{bmatrix}$$
$$= \begin{bmatrix} d^{\tau} & d^{\tau+1} \frac{(s+g)}{f} \\ 0 & d^{\tau} \end{bmatrix} = \begin{bmatrix} d^{\tau} & d^{\tau+1} \\ 0 & d^{\tau} \end{bmatrix}.$$

Thus

$$\gamma^{-1} \tau_d \gamma = \begin{pmatrix} 1 & d & d^{\tau} & d^{\tau+1} \\ 0 & 1 & 0 & d^{\tau} \\ 0 & 1 & d \\ 0 & 0 & 1 \end{pmatrix}.$$

Now let $\tau = \sigma^{-1}$. Then

$$\begin{pmatrix} 1 & b & b^{\tau} & b^{\tau+1} \\ 0 & 1 & 0 & b^{\tau} \\ 0 & 0 & 1 & b \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & a^{\sigma} & a & a^{\sigma+1} \\ 0 & 1 & 0 & a \\ & 1 & a^{\sigma} \\ & 0 & 1 \end{pmatrix} = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & a^{\sigma} \\ 0 & 1 \end{bmatrix}$$

for $b=a^{\sigma}$ and

$$\begin{pmatrix} 1 & 0 & & \\ 0 & a & & \\ & a^{\tau} & 0 & \\ & 0 & a^{\tau+1} \end{pmatrix} = \begin{pmatrix} 1 & 0 & & \\ 0 & d^{-2\sigma} & & \\ & d^{-2} & 0 & \\ & 0 & d^{-2-2\sigma} \end{pmatrix}$$

for $a = d^{-2\sigma}$. Multiplying by

$$\begin{bmatrix} d^{\sigma+1} & & \\ & d^{\sigma+1} & \\ & & d^{\sigma+1} \end{bmatrix}$$

of the kernel homology group, we obtain

$$\begin{bmatrix} d^{\sigma+1} & & \\ & d^{1-\sigma} & \\ & & d^{\sigma-1} \\ & & d^{-\sigma-1} \end{bmatrix} = \begin{bmatrix} d & & \\ & d^{-1} \end{bmatrix} \otimes \begin{bmatrix} d^{\sigma} & & \\ & & d^{-\sigma} \end{bmatrix}.$$

Hence, we may apply the results on tensor product planes with groups of order q(q-1).

Thus we obtain:

Theorem 3.21. Let π be a translation plane of order q^2 and kernel $K \cong GF(q)$, q even. Let H be a group in the linear translation complement of order q(q-1) and $HK^*/K^* \cong H$. Further, if S_2 is a Sylow 2-subgroup of H, assume the involutions are Baer and no two involutions fix the same subplane pointwise.

Then π is a tensor product plane and the spread is completely determined. A matrix spread set may be represented as follows:

$$\begin{aligned} x &= 0, \ y = x \begin{bmatrix} u & 0 \\ 0 & u \end{bmatrix}, \\ y &= x \begin{bmatrix} (a^{\sigma} + a + 1) \ c, \ (m_1 + a^{\sigma}(a^{\sigma} + 1)) \ c^{\sigma + 1} \\ c^{1 - \sigma} \ , \ (a + a^{\sigma}) \ c \end{bmatrix}, \\ y &= x \begin{bmatrix} (a^{\sigma} + a) \ c, \ (m_0 + a^{\sigma}(a^{\sigma} + 1)) \ c^{\sigma + 1} \\ c^{1 - \sigma} \ , \ (a + a^{\sigma} + 1) \ c \end{bmatrix} \end{aligned}$$

for all $u, a, c \neq 0$ of K, m_0, m_1 constants in K and $\sigma \in Aut K$ such that the fixed field of σ is GF(2) and $q=2^{2r+1}$.

NOTES 3.22. Several authors, [2], [3], [5], have recently studied translation planes of order q^2 that admit H groups of order q(q-1) where H is an autotopism group. In this situation, there are many different classes of nonisomorphic translation planes. So, we see that the assumption on the nature of the Sylow *p*-subgroups for $p^r = q$ is crucial in (3.21).

- (3.23) Open Problems and Related Questions.
- 1) (a) What are the Tensor Product Planes?
 - (b) Are there nontrivial generalized Ott-Schaeffer Planes?
- 2) Study translation planes of order q^2 , $p^r = q$ kernel GF(q) that admit linear collineation groups of order q(q-1): The Sylow *p*-subgroups are
 - (a) planar.
 - (b) quartic.
 - (a) 1) if planar the group is an autotropism group.
 - (a) 2) no two *p*-elements fix the same Baer subplane pointwise.

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