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ON CLASSIFICATION OF DYNAMICAL SYSTEMS WITH CROSS-SECTIONS

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1. Introduction

Let (M_i, \mathcal{F}_i) be a dynamical system on a manifold M_i with a cross-section X_i , where \mathcal{F}_i is the flow-structure, $i=1, 2$. To (M_i, \mathcal{F}_i) the associated diffeomorphism $f_i: X_i \rightarrow X_i$ is defined.

By S. Smale ([8], [9]), it is shown that if f_1 and f_2 are differentially or topologically conjugate by a map $h: X_1 \rightarrow X_2$, then (M_1, \mathcal{F}_1) and (M_2, \mathcal{F}_2) are differentially or topologically equivalent respectively.

The main purpose of this paper is to show the converse of the above fact under some conditions, that is; under the assumption that there exists no homomorphism of the fundamental group of one of the two cross-sections onto the infinite cyclic group, (M_1, \mathcal{F}_1) and (M_2, \mathcal{F}_2) are differentially or topologically equivalent if and only if f_1 and f_2 are differentially or topologically conjugate respectively (Theorem 4.1).

Furthermore we shall show an example of a pair of dynamical systems (M_1, \mathcal{F}_1) and (M_2, \mathcal{F}_2) with cross-sections X_1 and X_2 respectively such that the fundamental group of X_1 is isomorphic to the infinite cyclic group, and that (M_1, \mathcal{F}_1) and (M_2, \mathcal{F}_2) are differentially equivalent but the associated diffeomorphisms are not conjugate (§4).

As an application of Theorem (4.1), we shall show in §5 that for a given X satisfying the condition stated above concerning its fundamental group, there is a natural correspondence between the equivalence classes of dynamical systems (M, \mathcal{F}) with the cross-section X and the equivalence classes of smooth fibre bundles over S^1 with the fibre X (Theorem 5.3).

Another application will be shown in §6; that is classification of dynamical system on $S^n \times S^1 \# \tilde{S}^{n+1}$ with cross-section, where \tilde{S}^{n+1} denotes any homotopy sphere (Theorem 6.6). Here, it is essential that Γ^{n+1} classifies the differentially conjugate classes of diffeomorphisms on S^n .

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2. Terminology

Throughout this paper, all manifolds considered will be assumed to be compact and differentiable (C^∞).

A dynamical system or a flow \mathcal{F} on a manifold M is a 1-parameter group of transformations φ of M , where φ is a C^∞ -map $\varphi: R \times M \rightarrow M$ (R ; the real numbers) such that if we put $\varphi_t(x) = \varphi(t, x)$, then

- (i) $\varphi_0(x) = x$
- (ii) $\varphi_{t+s}(x) = \varphi_t \varphi_s(x)$,

and φ_t is a diffeomorphism $(M, \partial M) \rightarrow (M, \partial M)$. Here ∂M is the boundary of M .

By a pair (M, \mathcal{F}) we mean a dynamical system \mathcal{F} on a manifold M . (M_1, \mathcal{F}_1) and (M_2, \mathcal{F}_2) are said to be *differentiably (topologically) equivalent* if there is a diffeomorphism (homeomorphism) $h: M_1 \rightarrow M_2$ having the property that h maps every orbit of \mathcal{F}_1 onto an orbit of \mathcal{F}_2 preserving the orientation. Such a map h will be called an *equivalence*.

Two diffeomorphisms (homeomorphisms) $f_1: M_1 \rightarrow M_1$ and $f_2: M_2 \rightarrow M_2$ are said to be *differentiably (topologically) conjugate* if there exists a diffeomorphism (homeomorphism) $h: M_1 \rightarrow M_2$ such that $hf_1 = f_2h$.

A *cross-section* of a dynamical system (M, \mathcal{F}) or (M, φ) is a compact connected submanifold X of codimension 1 of M such that $\partial X \subset \partial M$, and that

- (i) X intersects every orbit,
- (ii) the intersection of X with each orbit is transversal,
- (iii) if $x \in X$, there is a $t > 0$ with $\varphi_t(x) \in X$, and
- (iv) if $x \in X$, there is a $t < 0$ with $\varphi_t(x) \in X$.

There can be no singular point of (M, \mathcal{F}) if there is a cross-section. $\partial X \neq \emptyset$ and $\partial M \neq \emptyset$, and X is properly imbedded in M , i.e. $\partial X \subset \partial M$ and $\text{Int } X \subset \text{Int } M$. By $(M, \mathcal{F}; X)$ we mean a dynamical system \mathcal{F} on a manifold M having a cross-section X .

For $(M, \mathcal{F}; X)$ we can define a map $f: X \rightarrow X$ by $f(x) = \varphi_{t_0}(x)$ where t_0 is the smallest positive t satisfying $\varphi_t(x) \in X$. $f: X \rightarrow X$ is a diffeomorphism; we call f the *associated diffeomorphism* of $(M, \mathcal{F}; X)$.

Conversely, suppose that a diffeomorphism f of X onto itself is given. Define a diffeomorphism $\tau: R \times X \rightarrow R \times X$ by $\tau(t, x) = (t+1, f^{-1}(x))$. Then the infinite cyclic group $\{\tau^m\} = Z$ operates freely on $R \times X$ and the orbit space $(R \times X)/Z$ is a manifold, say M_0 . The flow $\psi_t: R \times X \rightarrow R \times X$ defined by $\psi_t(u, x) = (u+t, x)$ induces a flow φ_t on M_0 . We call this (M_0, φ_t) the *suspension* of f . M_0 has a cross-section $X_0 = q(0 \times X) \subset M_0$, where $q: R \times X \rightarrow M_0$ is the quotient map.

The following properties are shown by S. Smale ([7] or [8]).

(2.1) *The associated diffeomorphism of $(M_0, \varphi_t; X_0)$ is differentiably conjugate to the given f .*

Furthermore

(2.2) *if $(M', \varphi'_i; X')$ is the suspension of the associated diffeomorphism of a dynamical system $(M, \varphi_i; X)$, then (M, φ_i) and (M', φ'_i) are differentiably equivalent (by an equivalence mapping X onto X').*

(2.3) *Let $(M_0, \mathcal{F}_0), (M_1, \mathcal{F}_1)$ be the suspensions of $f_0: X_0 \rightarrow X_0, f_1: X_1 \rightarrow X_1$ respectively. If f_0 and f_1 are differentiably (topologically) conjugate, then (M_0, \mathcal{F}_0) and (M_1, \mathcal{F}_1) are differentiably (topologically) equivalent.*

3. Lemmas

Suppose that $h: M' \rightarrow M$ is a differentiable (topological) equivalence between $(M', \mathcal{F}'; X')$ and $(M, \mathcal{F}; X)$. Let $f: X \rightarrow X$ be the associated diffeomorphism of $(M, \mathcal{F}; X)$. Let $p: R \times X \rightarrow X$ be the natural projection and $q: R \times X \rightarrow M_0$ the quotient map to the suspension M_0 of f . Using (2.2), we consider h to be a differentiable (topological) equivalence: $M' \rightarrow M_0$. Put $X_0 = hX' \subset M_0$ and let \tilde{X}_0 be a connected component of $q^{-1}(X_0)$. Then we have the following lemmas.

Lemma (3.1). *$q|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X_0$ is a covering. If h is a differentiable equivalence, then $q|_{\tilde{X}_0}$ is a smooth covering map.*

Proof. $q: R \times X \rightarrow M_0$ is a covering, furthermore q is a smooth covering.

Since X_0 is a properly imbedded submanifold of M_0 and since $q: (R \times X, q^{-1}(X_0)) \rightarrow (M, X_0)$ is a local homeomorphism, \tilde{X}_0 is a proper submanifold of $R \times X$. Since $q(\partial \tilde{X}_0) \subset \partial X_0, q(\text{Int } \tilde{X}_0) \subset \text{Int } X_0$, and since q is a local homeomorphism, the image $q(\tilde{X}_0)$ is a proper compact submanifold of X_0 with codimension 0. Therefore, $q|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X_0$ is an onto map.

Therefore it is easy to see that $q|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X_0$ is a covering and that if h is a differentiable equivalence, then it is a smooth covering.

Lemma (3.2). *If \tilde{X}_0 is compact, then $p|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X$ is a covering. If h is a differentiable equivalence $p|_{\tilde{X}_0}$ is a smooth covering.*

Proof. Since X' has transversal intersection with the flow in M' , and since h and q are local homeomorphisms mapping orbit onto orbit, \tilde{X}_0 has transversal intersection with the flow of $R \times X$. Hence, $p|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X$ is a local homeomorphism. Furthermore, as in (3.1), \tilde{X}_0 is a proper submanifold of $R \times X$, and $p: R \times X \rightarrow X$ maps boundary into boundary and maps interior into interior. Hence, $p(\tilde{X}_0)$ is a proper submanifold of X with codimension 0. Therefore, $p|_{\tilde{X}_0}$ is an onto-map.

For each x in X and each $\tilde{x}_i \in \tilde{X}_0$ in $p^{-1}(x)$ let $\tilde{U}(\tilde{x}) \in \tilde{X}_0$ be a neighbourhood such that $p|_{\tilde{U}(\tilde{x}_i)}$ is a homeomorphism and that if $\tilde{x}_i \neq \tilde{x}_j, \tilde{x}_i, \tilde{x}_j \in p^{-1}(x)$, then $\tilde{U}(\tilde{x}_i) \cap \tilde{U}(\tilde{x}_j) = \emptyset$, and let $U_i(x) \subset X$ be the homeomorphic image of $\tilde{U}(\tilde{x}_i)$ by p . Since \tilde{X}_0 is compact, it is clear that $p^{-1}(x)$ is a finite set. Put

$$W(x) = \bigcap_i U_i(x)$$

and

$$\tilde{W}(\tilde{x}_i) = (p^{-1}W(x)) \cap \tilde{U}(\tilde{x}_i).$$

Then, $W(x)$ and $\tilde{W}(\tilde{x}_i)$ satisfy the usual conditions for covering.

This proves that $p|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X$ is a covering.

Let $h: M' \rightarrow M$, X_0 , q , and $\tilde{X}_0 \subset R \times X$ be the same as in (3.1). It should be noted that one and only one of the two assumptions in the following lemmas (3.3) and (3.4) holds.

Lemma (3.3). *If there is $t_0 > 0$ such that $(t \times X) \cap \tilde{X}_0 = \phi$ for every t with $|t| > t_0$, then $q|_{\tilde{X}_0}$ is a diffeomorphism or a homeomorphism onto X_0 according that h is a differentiable or topological equivalence.*

Proof. Suppose there are two points $u, v \in \tilde{X}_0$ such that $q(u) = q(v) \in X_0$. Then for some integers i, j , ($i \neq j$), some $0 \leq t < 1$, and some $x \in X$, we have

$$u = \tau^i(t, x) \quad v = \tau^j(t, x),$$

where $\tau: R \times X \rightarrow R \times X$ is defined, as in §2, by $\tau(t, x) = (t+1, f^{-1}(x))$ (so that $\tau^i(t, x) = (t+i, f^{-i}(x))$). We may suppose $i < j$.

As \tilde{X}_0 is connected, there is a simple arc $C_0: I \rightarrow R \times X$ such that

$$\begin{aligned} C_0(s) &\in \tilde{X}_0 \quad \text{for any } 0 \leq s \leq 1, \\ C_0(0) &= u = \tau^i(t, x), \\ C_0(1) &= v = \tau^j(t, x). \end{aligned}$$

Next, for any integer r , we can define an arc $C_r: I \rightarrow R \times X$ by

$$C_r(s) = \tau^{r(j-i)} C_0(s).$$

Clearly $C_r(0) = C_{r-1}(1)$ and $qC_r = qC_0$ for any r , whence $C_r(I) \subset q^{-1}X_0$ for any r and $\bigcup_r C_r(I)$ is connected. Hence $\bigcup_r C_r(I) \subset \tilde{X}_0$, where $C_r(0) \in (t+i+r(j-i)) \times X$. Therefore \tilde{X}_0 does not satisfy the hypothesis of the lemma. This implies that the covering map $q|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X_0$ is a diffeomorphism or a homeomorphism, by (3.1), according that h is differentiable or topological. This completes the proof of (3.3).

Lemma (3.4). *If for any $t_0 > 0$, there is a $t \in R$ such that $|t| > t_0$ and $(t \times X) \cap \tilde{X}_0 \neq \phi$, then the covering of (3.1): $\tilde{X}_0 \rightarrow X_0$ is a regular covering with a transformation group isomorphic to Z .*

Proof. By the assumption, the covering is not trivial, since \tilde{X}_0 is not compact but X_0 is compact. Let $x_0 \in X_0$ be a base point of X_0 . If $\tilde{x}, \tilde{x}' \in \tilde{X}_0 \cap q^{-1}(x_0)$, then, by the definition of q , $\tilde{x}' = \tau^m \tilde{x}$ for some integer m .

Next, we shall show that this τ^m is a covering transformation of the covering: $\tilde{X}_0 \rightarrow X_0$. Let \tilde{y} be any point in \tilde{X}_0 . Since \tilde{X}_0 is connected, there is an arc C with the ends \tilde{x} and \tilde{y} . $\tau^m C$ is an arc in $q^{-1}X_0$ with the ends \tilde{x}' and $\tau^m \tilde{y}$. Since $\tilde{x}' \in \tilde{X}_0$ and \tilde{X}_0 is connected, we have $\tau^m \tilde{y} \in \tilde{X}_0$. Furthermore $q\tau^m y = q\tilde{y}$. Hence τ^m is a covering transformation of this covering.

Therefore $\tilde{X}_0 \rightarrow X_0$ is a regular covering.

Let i be the smallest positive integer such that $\tau^i \tilde{x} \in \tilde{X}_0$. We shall show that for any integer k , $\tau^{ki} \tilde{x} \in \tilde{X}_0$. Let C be an arc with the ends \tilde{x} and $\tau^i \tilde{x}$. Then, by repeating the argument above, $\tau^{(k-1)i} C \subset \tilde{X}_0$ if $k > 0$ and $\tau^{ki} C \subset \tilde{X}_0$ if $k < 0$. Therefore $\tau^{ki} \tilde{x} \in \tilde{X}_0$.

Further we shall show that for any point $\tau^m \tilde{x}$ in the fibre over x_0 , $m = ki$ for some integer k . Generally, we put $m = ki + h$, where k, h are integers and $0 \leq h < i$. If $h \neq 0$, $\tau^h \tilde{x}$ must exist in \tilde{X}_0 as above; it is a contradiction to the property of i . Therefore $m = ki$.

Hence the transformation group of the regular covering is isomorphic to Z . This completes the proof of (3.4).

Let $(M, \mathcal{F}; X)$ and $(M', \mathcal{F}'; X')$ be the suspensions of some C^∞ -automorphisms (diffeomorphisms) on X and X' respectively. Suppose that there exists a topological equivalence of dynamical systems, $h: M' \rightarrow M$. Let $q: R \times X \rightarrow M$, $p: R \times X' \rightarrow X$ and \tilde{X}_0 be the same as these in (3.1) and (3.2). And put $q_0 = q|_{\tilde{X}_0}$.

Lemma (3.5). *Suppose that \tilde{X}_0 satisfies the condition of (3.3), so that $q_0: \tilde{X}_0 \rightarrow h(X')$ is a homeomorphism. Then, $\pi_1(X') \cong \pi_1(X)$ by $i_* = (pq_0^{-1}h|_{X'})_*$.*

Proof. Since \tilde{X}_0 is homeomorphic to X' , $p|_{\tilde{X}_0}: \tilde{X}_0 \rightarrow X$ is a covering by (3.2). p induces the injection $p_*: \pi_1(\tilde{X}_0) \rightarrow \pi_1(X)$. Hence, if $j': X' \rightarrow M'$ denotes the including mapping, the composition $i = pq_0^{-1}hj': X' \rightarrow X$ induces an inclusion

$$i_*: \pi_1(X') \rightarrow \pi_1(X).$$

Let $j: X \rightarrow M$ denote the inclusion. We shall prove that the following diagram is commutative.

$$\begin{array}{ccc} \pi_1(X') & \xrightarrow{j'_*} & \pi_1(M') \\ i_* \downarrow & & h_* \downarrow \\ \pi_1(X) & \xrightarrow{j_*} & \pi_1(M) \end{array}$$

There is a homotopy

$$F_t: X' \rightarrow R \times X$$

such that

$$\begin{aligned} F_0 &= q_0^{-1}hj' \\ F_1 &= pq_0^{-1}hj'. \end{aligned}$$

In fact, F_t can be made easily by sliding $q_0^{-1}h(X')$ along the flow ψ_t of $R \times X$ onto X . Then,

$$G_t = qF_t : X' \rightarrow M$$

is a homotopy such that

$$\begin{aligned} G_0 &= hj' \\ G_1 &= jpq_0^{-1}hj' = ji. \end{aligned}$$

Therefore the diagram above is commutative.

We shall construct a smooth fibering $M \rightarrow S^1$ with fibre X from $(M, \mathcal{F}; X)$ (Cf. §5). Recall that $M = R \times X / \tau$, as in §2 and that $S^1 = R / t \sim t + 1$. The mapping: $R \times X \rightarrow R$ defined by $(t, x) \rightarrow t (t \in R, x \in X)$ induces a mapping: $R \times X / \tau \rightarrow R / t \sim t + 1$. This is a fibre map: $M \rightarrow S^1$.

In the same way, we construct a fibering: $M' \rightarrow S^1$ from $(M', \mathcal{F}'; X')$. Since the fibres X and X' are connected, we have the following commutative diagram, where the horizontal and vertical sequences are exact.

$$\begin{array}{ccccccc} & & 1 & & & & \\ & & \downarrow & & & & \\ 1 & \longrightarrow & \pi_1(X') & \xrightarrow{j'_*} & \pi_1(M') & \longrightarrow & Z \longrightarrow 1 \\ & & i_* \downarrow & & h_* \downarrow & & \\ 1 & \longrightarrow & \pi_1(X) & \xrightarrow{j_*} & \pi_1(M) & \longrightarrow & Z \longrightarrow 1 \end{array}$$

Then,

$$\begin{aligned} Z &\cong \pi_1(M) / \pi_1(X) \\ &\cong (\pi_1(M) / j_* i_* \pi_1(X')) / (\pi_1(X) / i_* \pi_1(X')). \end{aligned}$$

But,

$$\pi_1(M) / j_* i_* \pi_1(X') \cong \pi_1(M') / \pi_1(X') \cong Z,$$

whence,

$$Z \cong Z / (\pi_1(X) / i_* \pi_1(X')).$$

Hence it is necessary that

$$\pi_1(X) / i_* \pi_1(X') \cong 1.$$

Therefore $\pi_1(X') \cong \pi_1(X)$.

This completes the proof of (3.5).

4. Cross-section theorem

The purpose of this section is to prove

Theorem (4.1). *Let $(M, \mathcal{F}; X)$ and $(M', \mathcal{F}'; X')$ be dynamical systems with cross-sections. (Manifolds may have boundaries.) Suppose that there exists no*

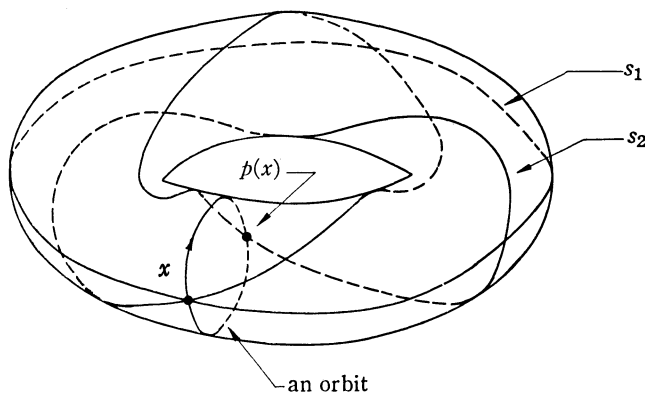
projection of the fundamental group $\pi_1(X)$ of X onto the infinite cyclic group Z .

Then (M, \mathcal{F}) and (M', \mathcal{F}') are differentiably (topologically) equivalent if and only if the associated diffeomorphisms of $(M, \mathcal{F}; X)$ and $(M', \mathcal{F}'; X')$ are differentiably (topologically) conjugate.

REMARK (4.2). The assumption in the theorem about the fundamental group is necessary. This is verified by the following.

Let $T=S_0 \times S_1$ be a torus, where S_j is a 1-dimensional circle, and let \mathcal{F} be the dynamical system on T such that any orbit of \mathcal{F} is $S_0 \times x \subset T$ for $x \in S_1$. Then $S_1 = * \times S_1$ in T ($* \in S_0$) is a cross-section of (T, \mathcal{F}) and the associated diffeomorphism of $(T, \mathcal{F}; S_1)$ is the identity map $i: S_1 \rightarrow S_1$.

Next, we imbed a circle in T in such a way that the imbedded image S_2 is a cross-section of (T, \mathcal{F}) and the associated diffeomorphism of $(T, \mathcal{F}; S_2)$ is the antipodal map $p: S_2 \rightarrow S_2$. This is possible. In fact, the imbedded image S_2 is a clover-knot, if we consider T to be located 3-dimensional euclidean space (see the figure).



Then S_1 and S_2 are two cross-sections of the same (therefore equivalent) dynamical system (T, \mathcal{F}) , but the associated diffeomorphisms i and g cannot be conjugate. In this case the fundamental groups of the cross-sections are isomorphic to Z .

Corollary (4.3). Let $(M, \mathcal{F}; X)$ and $(M', \mathcal{F}'; X')$ be dynamical systems with cross-sections. Suppose that the fundamental group $\pi_1(X)$ of X or the 1-dimensional homology group $H_1(X)$ is a finite group.

Then (M, \mathcal{F}) and (M', \mathcal{F}') are differentiably (topologically) equivalent if and only if the associated diffeomorphisms of $(M, \mathcal{F}; X)$ and $(M', \mathcal{F}'; X')$ are differentiably (topologically) conjugate.

Proof. This corollary is a direct consequence of (4.1).

In fact, if G is a finite group, there is no projection of G onto Z . If there

is a projection of $\pi_1(X)$ onto Z , the projection induces a projection of $\pi_1(X)/[\pi_1(X), \pi_1(X)]$ onto Z , where $[\pi_1(X), \pi_1(X)]$ denotes the commutator subgroup. And $\pi_1(X)/[\pi_1(X), \pi_1(X)]$ is isomorphic to $H_1(X)$.

Corollary (4.4). *Assume that for $(M_1, \mathcal{F}_1; X_1)$ and $(M_2, \mathcal{F}_2; X_2)$, (M_1, \mathcal{F}_1) and (M_2, \mathcal{F}_2) are differentiably (topologically) equivalent and that M_1 and M_2 are closed (so that X_1 and X_2 are closed). Suppose that one of the following two conditions is satisfied.*

- i) *There exists no projection of $\pi_1(X_1)$ onto Z .*
- ii) *There exists $(\tilde{M}_i, \tilde{\mathcal{F}}_i; \tilde{X}_i)$ ($i=1, 2$) satisfying the following conditions.*
 - (a) $\partial\tilde{M}_i = M_i, \partial\tilde{X}_i = X_i$.
 - (b) $\tilde{\mathcal{F}}_i$ is an extension of \mathcal{F}_i .
 - (c) $(\tilde{M}_1, \tilde{\mathcal{F}}_1)$ and $(\tilde{M}_2, \tilde{\mathcal{F}}_2)$ are differentiably (topologically) equivalent.
 - (d) *There exists no projection of $\pi_1(\tilde{X}_1)$ onto Z .*

Then the associated diffeomorphisms of $(M_1, \mathcal{F}_1; X_1)$ and $(M_2, \mathcal{F}_2; X_2)$ are differentiably (topologically) conjugate.

Proof of Theorem (4.1). If the associated diffeomorphisms of $(M, \mathcal{F}; X)$ and $(M', \mathcal{F}'; X')$ are differentiably (topologically) conjugate, (2.2) and (2.3) imply that (M, \mathcal{F}) and (M', \mathcal{F}') are differentiably (topologically) equivalent.

Next, we shall prove the converse of this, assuming that there is no projection of $\pi_1(X')$ onto Z . The proof consists of two parts; the first, to find a diffeomorphism (homeomorphism) of X' onto X , and the second, to prove that the diffeomorphism (homeomorphism) satisfies the condition of conjugacy.

Let $h: M' \rightarrow M$ be the differentiable (topological) equivalence of (M, \mathcal{F}) and (M', \mathcal{F}') . Here, by (2.1) and (2.2) we may regard $(M, \mathcal{F}; X)$ as $(M_0, \mathcal{F}_0; X)$, the suspension of the associated diffeomorphism of $(M, \mathcal{F}; X)$, and may regard $(M', \mathcal{F}'; X')$ similarly.

Part 1. Let $q: R \times X \rightarrow M$ be the suspending projection as in §2. Then, by (3.1), $q: \tilde{X}_0 \rightarrow X_0$ is a covering map, where $X_0 = h(X')$ and \tilde{X}_0 is any connected component of $q^{-1}(X_0)$.

Suppose further that for any $t_0 > 0$ there is a t such that $|t| > t_0$ and $(t \times X) \cap \tilde{X}_0 \neq \emptyset$. Then by (3.4) this covering $\tilde{X}_0 \rightarrow X_0$ is a regular covering with the transformation group isomorphic to Z and we have an exact sequence

$$1 \longrightarrow \pi_1(\tilde{X}_0) \longrightarrow \pi_1(X_0) \longrightarrow Z \longrightarrow 1.$$

This is a contradiction to the assumption of $\pi_1(X') \cong \pi_1(X_0)$. Therefore, by (3.3), any component \tilde{X}_0 of $q^{-1}(X_0)$ is diffeomorphic (homeomorphic if h is a homeomorphism) to X_0 .

Therefore \tilde{X}_0 is a compact differentiable (topological) submanifold of $R \times X$. Hence, by (3.2), $p: \tilde{X}_0 \rightarrow X$ is a differentiable (topological) covering, where p is

the natural projection $R \times X \rightarrow X$. Since \tilde{X}_0 is diffeomorphic (homeomorphic) to X' , we get a differentiable (topological) covering map $i = pq_0^{-1}h: X' \rightarrow X$, where $q_0 = p|_{\tilde{X}_0}$. Therefore, since i_* is an isomorphism of $\pi_1(X')$ onto $\pi_1(X)$ by (3.5), $pq_0^{-1}h$ is a diffeomorphism (homeomorphism if h is a topological equivalence): $X' \rightarrow X$.

Part 2. Since any component of $q^{-1}(X_0)$ is homeomorphic to X_0 by q , any component of $q^{-1}(X_0)$ is $\tau^i \tilde{X}_0$ for some integer i , where \tilde{X}_0 is a fixed component and τ is defined, as above, by

$$\tau(t, x) = (t+1, f^{-1}(x)), \quad t \in R, x \in X.$$

In order to prove Part 2, we shall prove the following lemma.

Lemma (4.5). *Suppose that $\tau^i \tilde{X}_0$ is homeomorphic to X by the map p and that $(s, x) \in \tau^i \tilde{X}_0, (t, x) \in \tau^j \tilde{X}_0$. Then, $s < t$ if and only if $i < j$.*

Proof. Since $t = s$ whenever $i = j$, it is sufficient if we can prove that $i < j$ implies $s < t$.

Here, we suppose that there exist integers i, j , real numbers $t, s \in R$ and a point $x \in X$ satisfying the conditions of the lemma, such that $s > t$ and $i < j$.

Since $p: \tau^i \tilde{X}_0 \rightarrow X$ is homeomorphism, $\tau^i \tilde{X}_0$ splits $R \times X$ for any i ; that is, if $(s_1, x_1), (s_2, x_2) \in \tau^i \tilde{X}_0$ and $(t, x_1) \in \tau^j \tilde{X}_0$, and if $s_1 < t$, then there is $t_2 \in R$ such that $(t_2, x_2) \in \tau^j \tilde{X}_0$ and $s_2 < t_2$.

By assumption we have

$$(s+j-i, f^{i-j}(x)) = \tau^{j-i}(s, x) \in \tau^j \tilde{X}_0, \quad j-i > 0.$$

By the splitting property and by $s > t$, there is a $s_1 \in R$ such that

$$(s_1, f^{i-j}(x)) \in \tau^i \tilde{X}_0, \quad s_1 > s+j-i.$$

By repeating this process we get $s_r \in R$ for all r such that

$$(s_r, f^{r(i-j)}(x)) \in \tau^i \tilde{X}_0, \quad s_r > s+r(j-i).$$

But this is in contradiction to the fact that $\tau^i \tilde{X}_0$ is compact. This completes the proof of the lemma.

Now, we come back to the proof of Part 2.

Let $(t, x) \in \tilde{X}_0 \subset R \times X$. The orbit of $R \times X$ passing through $(t, x) \in \tilde{X}_0$ meets $q^{-1}(X_0)$ at $(s, x) \in \tau \tilde{X}_0$ for the first time. Define a diffeomorphism (homeomorphism) $g: \tilde{X}_0 \rightarrow \tau \tilde{X}_0$ by $g(t, x) = (s, x)$.

Now we can easily see, by (4.5), that the following diagram is comutative.

$$\begin{array}{ccccccc} X' & \xrightarrow{h} & X_0 & \xrightarrow{q_0^{-1}} & \tilde{X}_0 & \xrightarrow{p} & X \\ f' \downarrow & & f_0 \downarrow & & \downarrow \tau^{-1}g & & \downarrow f \\ X' & \xrightarrow{h} & X_0 & \xrightarrow{q_0^{-1}} & \tilde{X}_0 & \xrightarrow{p} & X \end{array}$$

Here $f_0: X \rightarrow X_0$ is a diffeomorphism (homeomorphism) defined as follows; if $x \in X_0$, $f_0(x)$ is the point where the orbit of (M, \mathcal{F}) passing through x meet X_0 for the first time.

The commutativity of the diagram implies that f and f' are differentially or topologically conjugate, according that h is differentiable or topological. This completes the proof of Part 2.

Therefore the proof of Theorem (4.1) is completed.

We deduce the following corollary directly from (4.1).

Corollary (4.6). *Let X and X' be two cross-sections of a dynamical system. If there exists no projection of $\pi_1(X)$ onto Z , then X and X' are diffeomorphic.*

Remark (4.2) is not applicable to this corollary. In a paper in preparation¹⁾, we will show examples of dynamical systems with two cross-sections which are not diffeomorphic or homeomorphic.

5. Relation with fibre bundles

All fibre bundles considered in this section are assumed to be smooth and to have the base space S^1 and the group $\text{Diff}(X)$, in the sense of [10], where $\text{Diff}(X)$ is the group of diffeomorphisms of the fibre X onto itself. We consider the discrete topology in $\text{Diff}(X)$.

Let X_f be the *mapping torus* of f defined by $X_f = I \times X$ with identification $(0, f(x)) = (1, x)$ for all $x \in X$. If f is a diffeomorphism, X_f is a smooth manifold. For any diffeomorphism f of X onto itself, let ξ_f be the fibre bundle $p: X_f \rightarrow I/0 \sim 1 = S^1$ defined by $p(t, x) = t$. Moreover,

(5.1) *for any fibre bundle ξ with fibre X , there exists a diffeomorphism f over X such that ξ_f is equivalent to ξ in $\text{Diff}(X)$, in the sense of [10].*

Let $\text{Hom}(X)$ be the group of homeomorphism of X onto itself. We consider the discrete topology in it. Let $[\xi]_d$ and $[\xi]_t$ be the equivalence classes in $\text{Diff}(X)$ and $\text{Hom}(X)$ respectively containing the fibre bundle ξ . Then,

(5.2) $[\xi_f]_d = [\xi_g]_d$ ($[\xi_f]_t = [\xi_g]_t$) *if and only if f and g are differentially (topologically) conjugate.*

Let $[(M, \mathcal{F})]_d$ be the differentiable equivalence class containing a dynamical system (M, \mathcal{F}) , and $[(M, \mathcal{F})]_t$ the topological equivalence class having the same property. And set

$$\begin{aligned} \mathcal{F}_d(X) &= \{[(M, \mathcal{F})]_d; (M, \mathcal{F}) \text{ has a cross-section } X\}, \\ \mathcal{F}_t(X) &= \{[(M, \mathcal{F})]_t; \text{—————} \}, \\ \mathcal{F}_d(X) &= \{[\xi]_d; \xi \text{ has a fibre } X\}, \\ \mathcal{F}_t(X) &= \{[\xi]_t; \text{—————} \}. \end{aligned}$$

1) G. Ikegami: *On dynamical systems with cross-sections*, (to appear).

We define a map $\eta_d: F_d(X) \rightarrow \mathcal{F}_d(X)$ (similarly for $\eta_t: F_t(X) \rightarrow \mathcal{F}_t(X)$) as follows; Let $[\xi]_d \in F_d(X)$, then by (5.1) there is f with $\xi_f \in [\xi]_d$. We define $\eta_d[\xi]_d$ by the differentiable equivalence class of the dynamical system which is the suspension of f . Here, η_d is well defined; in fact by (5.2) and (2.3), η_d is independent of the selection of f .

In order to define the mapping $\mu_d: \mathcal{F}_d(X) \rightarrow F_d(X)$ (similarly for $\mu_t: \mathcal{F}_t(X) \rightarrow F_t(X)$), we must suppose that there is no projection of $\pi_1(X)$ onto Z . In this case, for any $[(M, \mathcal{F})]_d \in \mathcal{F}_d(X)$, $\mu_d[(M, \mathcal{F})]_d$ is defined by $[\xi_f]_d \in F_d(X)$, where f is the associated diffeomorphism of $(M, \mathcal{F}; X)$. μ_d is well defined; in fact, by (4.1) and (5.2), μ_d is independent of the selection of (M, \mathcal{F}) and X .

Here, $\mu_d \eta_d = \text{identity}$ ($\mu_t \eta_t = \text{identity}$) by (2.1) and $\eta_d \mu_d = \text{identity}$ ($\eta_t \mu_t = \text{identity}$) by (2.2).

Therefore we have proved the next theorem;

Theorem (5.3). *If there exist no projection of $\pi_1(X)$ onto Z , then there is a natural one-to-one correspondence between $\mathcal{F}_d(X)$ and $F_d(X)$ ($\mathcal{F}_t(X)$ and $F_t(X)$).*

6. Dynamical systems on tori with cross-section

The purpose of this section is to prove Theorem (6.6).

Define the two fibre maps,

$$\begin{aligned} p_+ : S^n \times S^1 &\rightarrow S^1 & \text{by } p_+(x, y) &= y, \\ p_- : S^n \times S^1 &\rightarrow S^1 & \text{by } p_-(x, y) &= r(y), \end{aligned}$$

for any $x \in S^n, y \in S^1$, where $r: S^1 \rightarrow S^1$ denotes an arbitrarily given homeomorphism of order -1 .

The following lemma is concerned only with topology.

Lemma (6.1). *If $n \geq 2$, any fibre map $p: S^n \times S^1 \rightarrow S^1$ with connected fibre is homotopic either to p_+ or to p_- .*

Proof. Denote by $\pi(X; Y)$ the set of homotopy classes of the maps: $X \rightarrow Y$ with fixed base points.

First, we shall show $\pi(S^n \times S^1; S^1) \cong Z$. Let $i: S^n \vee S^1 \rightarrow S^n \times S^1$ be the natural injection, where \vee denotes the union in identifying the base points, and let $h: S^n \times S^1 \rightarrow (S^n \times S^1)/(S^n \vee S^1) = S^{n+1}$ be the natural projection. We have an exact sequence (Puppe sequence);

$$\pi(S^{n+1}; S^1) \xrightarrow{h^*} \pi(S^n \times S^1; S^1) \xrightarrow{i^*} \pi(S^n \vee S^1; S^1).$$

Here,

$$\pi(S^{n+1}; S^1) \cong 0$$

and

$$\pi(S^n \vee S^1; S^1) \cong \pi(S^n; S^1) + \pi(S^1; S^1) \cong Z.$$

Moreover, we can easily see that i^* is a projection. Therefore,

$$\pi(S^n \times S^1; S^1) \cong \pi_1(S^1) \cong Z.$$

Let this isomorphism $\pi(S^n \times S^1; S^1) \rightarrow \pi_1(S^1)$ be denoted by the same i^* .

Next, we shall show that, for a fibre map p with connected fibre F , $i^*([p])$ is a generator of $\pi_1(S^1)$. Where $[p]$ denotes the element of $\pi(S^n \times S^1; S^1)$ containing p .

Let

$$\longrightarrow \pi_1(S^n \times S^1) \xrightarrow{p_*} \pi_1(S^1) \longrightarrow \pi_0(F)$$

be the homotopy exact sequence of the fibre space. Since $\pi_0(F)=0$ and since $\pi_1(S^n \times S^1)$ and $\pi_1(S^1)$ are isomorphic to Z , p_* is an isomorphism. If $j: S^1 \rightarrow S^n \times S^1$ is the natural inclusion, $j_*: \pi_1(S^1) \rightarrow \pi_1(S^n \times S^1)$ is an isomorphism. And if 1 is the generator of $\pi_1(S^1)$ preserving the orientation of S^1 , we have

$$p_*j_*(1) = i^*([p]).$$

Since $p_*j_*(1)$ is q generator of $\pi_1(S^1)$, $i^*([p]) = \pm 1$. But, $i^*([p_+]) = 1$ and $i^*([p_-]) = -1$. Therefore $[p] = [p_+]$ or $[p_-]$.

This completes the proof of (6.1).

Let $\text{Diff}_+(S^n)$ and $\text{Diff}_+(D^{n+1})$ denote the groups of orientation preserving diffeomorphisms on S^n and on a disk D^{n+1} resp., and let $r: \text{Diff}_+(D^{n+1}) \rightarrow \text{Diff}_+(S^n)$ denote the homomorphism obtained by the restriction. Then, the group $\mathcal{D}(S^n) = \text{Diff}_+(S^n) / \text{Image } r$ is isomorphic to $\Gamma^{n+1}([4])$. Here Γ^{n+1} denotes the group of differentiable structures on S^{n+1} with usual $p.1.$ structure under the connected sum operation $\#$. $\mathcal{D}(S^n)$ is an abelian group [6]. If $n \geq 4$ or $n=1$, Γ^{n+1} is the same as θ^{n+1} , which is by definition the group of homotopy $(n+1)$ -sphres ([3]).

Let $\mathcal{S}(S^n \times S^1)$ denote the set of all differentiable manifolds homeomorphic to $S^n \times S^1$ classified by diffeomorphisms and let

$$\psi: \Gamma^{n+1} \longrightarrow \mathcal{S}(S^n \times S^1)$$

be the mapping defined by $\Psi(\tilde{S}^{n+1}) = S^n \times S^1 \# \tilde{S}^{n+1}$, $\tilde{S}^{n+1} \in \Gamma^{n+1}$. Next, define a mapping

$$\Phi: \text{Diff}_+(S^n) \longrightarrow \mathcal{S}(S^n \times S^1)$$

by $\Phi(f) = S^n_f$ for any $f \in \text{Diff}_+(S^n)$.

Lemma (6.2). Φ induces a one-to-one correspondence $\tilde{\Phi}: \mathcal{D}(S^n) \rightarrow \Psi(\Gamma^{n+1})$. Moreover, if $[f] \in \mathcal{D}(S^n)$ then $\tilde{\Phi}([f]) = S^n \times S^1 \# \tilde{S}^{n+1}$, where $\tilde{S}^{n+1} \in \Gamma^{n+1}$ is the

element corresponding to $[f]$ under the isomorphism of $\mathcal{D}(S^n)$ with Γ^{n+1} .

Proof. For any \tilde{S}^{n+1} in Γ^{n+1} , $S^n \times S^1 \# \tilde{S}^{n+1}$ is diffeomorphic to S^n_f , where f is any diffeomorphism in the element of $\mathcal{D}(S^n)$ corresponding to $\tilde{S}^{n+1} \in \Gamma^{n+1}$ under the isomorphism. (See [1], Lemma 1.) Therefore Φ can be well-defined and Φ maps $\mathcal{D}(S^n)$ onto $\Psi(\Gamma^{n+1})$.

Moreover, for any $\tilde{S}_1^{n+1}, \tilde{S}_2^{n+1} \in \Gamma^{n+1}$ with $\tilde{S}_1^{n+1} \# \tilde{S}_2^{n+1}$,

$$S^n \times S^1 \# \tilde{S}_1^{n+1} \# S^n \times S^1 \# \tilde{S}_2^{n+1} \quad \text{in } \mathcal{S}(S^n \times S^1),$$

because, if

$$S^n \times S^1 \# \tilde{S}_1^{n+1} = S^n \times S^1 \# \tilde{S}_2^{n+1} \quad \text{in } \mathcal{S}(S^n \times S^1),$$

then

$$S^n \times S^1 \# \tilde{S}_1^{n+1} \# (-\tilde{S}_2^{n+1}) = S^n \times S^1$$

by using an orientation-preserving diffeomorphism. But, the inertia group of $S^n \times S^1$: $I(S^n \times S^1) = \{\tilde{S}^{n+1} \in \Gamma^{n+1}; S^n \times S^1 \# \tilde{S}^{n+1} = S^n \times S^1\}$ is equal to 0 for all n (see [11], [2], [6])¹⁾. Hence, $\tilde{S}_1^{n+1} \# (-\tilde{S}_2^{n+1}) = 0$ in Γ^{n+1} . This implies \tilde{S}_1^{n+1} is diffeomorphic to \tilde{S}_2^{n+1} . Therefore Φ is an injection.

These prove the lemma.

Proposition (6.3). *If $f, g \in \text{Diff}_+(S^n)$ are differentiably conjugate²⁾, then f and g are contained in the same element of $\mathcal{D}(S^n)$ ³⁾.*

Proof. If f and g are differentiably conjugate, S^n_f and S^n_g are diffeomorphic. Then, (6.2) implies $[f] = [g]$ in $\mathcal{D}(S^n)$.

We denote by $\mathcal{C}(\tilde{S}^{n+1})$ the set of differentiably conjugate classes of diffeomorphisms contained in the element of $\mathcal{D}(S^n)$ corresponding to $\tilde{S}^{n+1} \in \Gamma^{n+1}$.

The following property is due to W. Browder ([1], Lemma 2).

(6.4) *Let mapping tori X_f and Y_g be the total spaces of differentiable fibre bundles over S^1 with projection p and q , and with fibres X^n and Y^n which are 1-connected closed manifolds of dimension $n \geq 5$. If $h: X_f \rightarrow Y_g$ is a diffeomorphism such that qh is homotopic to p , then there is a diffeomorphism h' such that $qh' = p$, so that h' restricts to a diffeomorphism of X with Y .*

If $M^{n+1} \in \mathcal{S}(S^n \times S^1)$ for $n \geq 5$, any smooth fibre bundle over S^1 with total space M^{n+1} and with connected fibre has fibre with the homotopy groups of sphere, which is homeomorphic to S^n by [7] or [5], p. 109, Prop. B. The following lemma shows a condition for fibre to be diffeomorphic to S^n .

1) If $n \geq 4$, $I(S^n \times S^1) = 0$ by the method in [11]; and if $n > 4$, $I(S^n \times S^1) = 0$, since $\Gamma^{n+1} = 0$ by [2] for $n = 3$ and by [6] for $n \leq 2$.

2) If f and g are conjugate, there is a $h \in \text{Diff}(S^n)$ with $hf = gh$. But we should notice that the definition of conjugacy in § 2 does not imply that h preserves orientation. If h preserves orientation, (6.3) is trivial. Because, we can consider $h \in \mathcal{D}(S^n)$, and the group $\mathcal{D}(S^n)$ is abelian.

3) By using J. Cerf's theorem to (6.4) we have; *If $f, g \in \text{Diff}_+(S^n)$ are differentiably conjugate, and $n \geq 8$, then f and g are isotopic.*

Lemma (6.5). *Suppose M^{n+1} is in $\Psi(\Gamma^{n+1})$, $n \geq 5$ or $n=2$, then the fibre of any smooth fibre bundle over S^1 with total space M and with connected fibre is diffeomorphic to S^n .*

Proof. By (6.2) there is $f \in \text{Diff}_+(S^n)$ such that S^n_f is diffeomorphic to M^{n+1} . Let $p_+ : S^n_f \rightarrow S^1$ be the fibre bundle defined by $p(t, x) = t$, as in §5. Put $p_- = rp_+$, where $r : S^1 \rightarrow S^1$ is a diffeomorphism with degree -1 . And let $q : M^{n+1} \rightarrow S^1$ be any smooth fibre bundle with connected fibre. q is homotopic either to p_+ or to p_- by (6.1). Hence, if $n \geq 5$, (6.4) implies that the fibre of q is diffeomorphic to the fibre S^n of p_+ or of p_- . If $n=2$, the Lemma is trivial, since $\theta^2 = \Gamma^2 = 0$.

Theorem (6.6). *If M^{n+1} ($n \geq 5$ or $n=2$) is diffeomorphic to $S^n \times S^1 \# \tilde{S}^{n+1}$ for some \tilde{S}^{n+1} in Γ^{n+1} , then the differentiable equivalence classes of dynamical systems on M with cross-sections have a one-to-one correspondence with $\mathcal{C}(\tilde{S}^{n+1})$. The class corresponding to $f \in \mathcal{C}(\tilde{S}^{n+1})$ is the suspension of f .*

Proof. Let $(M, \mathcal{F}; X)$ denote any dynamical system on M^{n+1} with cross-section. M is diffeomorphic to X_f , where f is the associated diffeomorphism of $(M, \mathcal{F}; X)$. Since there is a smooth fibre bundle $X_f \rightarrow S^1$, (6.5) implies that X is diffeomorphic to S^n . Hence, any differentiable equivalence class of dynamical systems on M with cross-sections is in $\mathcal{F}_d(S^n)$, for which (5.3) is a one-to-one correspondence to $F_d(S^n)$. And, by (5.1) and (5.2) there exists a one-to-one correspondence between the differentiably conjugate classes of diffeomorphisms on S^n and $F_d(S^n)$. Therefore (6.2) and (6.3) imply that the differentiable equivalence classes of dynamical systems on M^{n+1} correspond to $\mathcal{C}(\tilde{S}^{n+1})$. This completes the proof of the theorem.

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