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***On the Normal Forms of Differential Equations in  
 the Neighborhood of an Equilibrium Point***

By Mitio NAGUMO and Kusuo ISÉ

**§ 1. Introduction.**

1. In this note we use the notations  $\partial_i u$  and  $\partial_{i,j}^2 u$  for  $\frac{\partial}{\partial x_i} u$  and  $\frac{\partial^2}{\partial x_i \partial x_j} u$  respectively. The vectors  $(x_1, \dots, x_m)$  and  $(y_1, \dots, y_m)$  in  $R^m$  will be denoted briefly by  $x$  and  $y$  respectively.

Let  $A=(a_{ij})$  be a constant real  $(m, m)$ -matrix, all of whose characteristic roots  $\lambda_i$  ( $i=1, \dots, m$ ) have non-zero real parts, and  $f(x)=(f_1(x), \dots, f_m(x))$  a real vector function of class  $C^1$  on some neighborhood of  $x=0$ , such that  $f(0)=0$  and  $|\partial_x f(x)| \leq K \cdot |x|$  with a constant  $K > 0$  where

$$|x| = \left( \sum_i x_i^2 \right)^{\frac{1}{2}}, \quad |\partial_x f(x)| = \left\{ \sum_{i,j} (\partial_i f_j(x))^2 \right\}^{\frac{1}{2}}.$$

We consider the autonomous systems

$$(1.1) \quad \frac{dx}{dt} = A \cdot x + f(x)$$

and

$$(1.2) \quad \frac{dy}{dt} = A \cdot y,$$

regarding  $x, y$  and  $f(x)$  as the column-vectors. The purpose of this note is to show that, under some conditions on  $\lambda_i$  ( $i=1, \dots, m$ ) and  $f(x)$ , the system (1.1) can be transformed into (1.2) by a change of variables

$$(1.3) \quad y = x + u(x)$$

where  $u(x) = (u_1(x), \dots, u_m(x))$  is a real vector function of class  $C^1$ , such that

$$(1.4) \quad \begin{cases} u(0) = 0 \\ |\partial_x u(x)| \leq L \cdot |x| \end{cases}$$

with some constant  $L > 0$ .

When  $f(x)$  is analytic regular in  $x$ , in order to show the existence of the transformation given by (1.3) with analytic regular  $u(x)$ , we must necessarily assume that there exist no relations of the form

$$(1.5) \quad \lambda_i = \sum_{j=1}^m n_j \cdot \lambda_j$$

where  $n_j$  ( $j=1, \dots, m$ ) are non-negative integers such that  $\sum_{j=1}^m n_j > 1$ .

As to this case, some results were obtained by H. Poincaré, C. L. Siegel, and others, while we obtain the present result for the real systems with a transformation of class  $C^1$  under some weaker conditions.

## § 2. Main Theorem.

### 2. Theorem. Assumptions:

(i)  $A$  is a constant real  $(m, m)$ -matrix, all of whose characteristic roots  $\lambda_i$  ( $i=1, \dots, m$ ) have non-zero real parts:  $\Re(\lambda_i) \neq 0$  ( $i=1, \dots, m$ ).

(ii) Let

$$(2.1) \quad f_i(x) = p_i(x) + q_i(x) \quad (i=1, \dots, m)$$

where  $p_i(x)$  are polynomials in  $x$  with real coefficients such that  $p_i(0) = \partial_j p_i(0) = 0$  ( $i=1, \dots, m; j=1, \dots, m$ ), and  $q_i(x)$  ( $i=1, \dots, m$ ) are real-valued functions of class  $C^1$  satisfying

$$(2.2) \quad \begin{cases} q(0) = 0 \\ |\partial_x q(x)| \leq Q \cdot |x|^h \end{cases}$$

with some integer  $h > 0$  and some constant  $Q > 0$ .

(iii) There exist no relations of the form

$$\lambda_i = \sum_{j=1}^m n_j \cdot \lambda_j$$

where  $n_j$  ( $j=1, \dots, m$ ) are non-negative integers such that

$$h > \sum_{j=1}^m n_j > 1.$$

*Conclusion:* There exists a positive constant  $h_0$ , depending only on  $\lambda_i$  ( $i=1, \dots, m$ ), with the following property: if  $h > h_0$ , there exist functions  $u_i(x)$  ( $i=1, \dots, m$ ) of class  $C^1$  satisfying (1.4), such that the system (1.1) is reduced to the form (1.2) by the substitution (1.3).

3. If (1.1) is transformed into (1.2) by (1.3),  $u(x)$  must satisfy the system of partial differential equations

$$(3.1) \quad \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i(x) \right) \cdot \partial_i u_\nu = \sum_{\mu=1}^m a_{\nu\mu} u_\mu - f_\nu(x) \quad (\nu = 1, \dots, m).$$

For we have, by operating  $\frac{d}{dt}$  on both sides of (1.3),

$$\frac{dy_i}{dt} = \frac{dx_i}{dt} + \sum_{\nu=1}^m \partial_\nu u_i \cdot \frac{dx_\nu}{dt} \quad (i = 1, \dots, m)$$

from which (3.1) follows immediately by (1.1), (1.2) and (1.3). Conversely, if  $u(x)$  is any function satisfying (3.1), then the substitution (1.3) will transform (1.1) into (1.2). Thus we have only to show the existence of  $u(x)$  satisfying (1.4) and (3.1), if  $h$  is sufficiently large.

### § 3. Auxiliary Theorem.

4. In this section we consider the system of semi-linear partial differential equations

$$(4.1) \quad \sum_{i=1}^m P_i(x) \cdot \partial_i u_\nu = Q_\nu(x, u) \quad (\nu = 1, \dots, l)$$

where  $x = (x_1, \dots, x_m)$  and  $u = (u_1, \dots, u_l)$  denote real vectors in  $R^m$  and  $R^l$  respectively. Let  $P_i(x)$  be real-valued functions of class  $C^1$  in an open domain  $D \subset R^m$ , such that

$$(4.2) \quad (P_1(x), \dots, P_m(x)) \neq (0, \dots, 0) \quad (x \in D).$$

And  $Q_\nu(x, u)$  be real-valued functions of class  $C^1$  in

$$\Omega = \{(x, u) \in R^{m+l} : x \in D, |u| \leq \omega(x)\}$$

where  $\omega(x)$  is some positive-valued function of class  $C^1$  in  $D$ . A curve  $x = x(t)$  in  $R^m$  is said to be a *base characteristic* of (4.1) if  $x(t)$  satisfies the following system of ordinary differential equations:

$$(4.3) \quad \frac{dx_i}{dt} = P_i(x) \quad (i = 1, \dots, m).$$

Let an  $(m-1)$ -dimensional manifold  $M$  in  $R^m$  be given by

$$(4.4) \quad M: x_i = A_i(s_1, \dots, s_{m-1}) \quad (i = 1, \dots, m)$$

where  $A_i(s)$  are functions of class  $C^1$  in some domain  $S \subset R^{m-1}$  such that  $A(s) = (A_1(s), \dots, A_m(s)) \in D$  for  $s = (s_1, \dots, s_{m-1}) \in S$ . We assume that

$$(4.5) \quad \left| \begin{matrix} P_i(A(s)), \partial_j A_i(s) & i \downarrow 1, \dots, m \\ & j \rightarrow 1, \dots, m-1 \end{matrix} \right| \neq 0 \quad \text{for } s \in S$$

and that any base characteristic

$$(4.6) \quad x = x(t, s),$$

issuing from a point of  $M$  so that  $x(0, s) = A(s)$ , exists on the interval:  $0 \leq t < \tau(s)$  where  $\tau(s)$  is a continuous function on  $S$ , and that the set  $X = \{x = x(t, s) : 0 \leq t < \tau(s), s \in S\}$  is filled up only onefold with all those curves  $x = x(t, s) (s \in S)$ , i.e. to any point  $x \in X$  there corresponds just one  $(t, s)$  such that  $x = x(t, s), 0 \leq t < \tau(s), s \in S$ . Then we have easily

$$\frac{\partial(x_1, \dots, x_m)}{\partial(t, s_1, \dots, s_{m-1})} = \left| \begin{matrix} P_i(A(s)), \partial_j A_i(s) & i \downarrow 1, \dots, m \\ & j \rightarrow 1, \dots, m-1 \end{matrix} \right| \cdot \exp \left( \int_0^t \sum_{i=1}^m \partial_i P_i(x)_{x=x(t,s)} dt \right) \neq 0,$$

which shows that the 1-1 mapping (4.6) from  $\{(t, s) : s \in S, 0 \leq t < \tau(s)\}$  onto  $X$  and its inverse are both of class  $C^1$ .

By (4.6) the system (4.1) is reduced to the following system of ordinary differential equations,  $s$  being a parameter :

$$(4.7) \quad \frac{du_\nu}{dt} = Q_\nu(x(t, s), u) \quad (\nu = 1, \dots, l).$$

We have then

$$\partial_i \omega(x(t, s)) = \left[ \sum_{i=1}^m P_i(x) \cdot \partial_i \omega(x) \right]_{x=x(t,s)}$$

and

$$\partial_i |u(t, s)| \cdot |u(t, s)| = \sum_{\nu=1}^l u_\nu(t, s) \cdot Q_\nu(x(t, s), u(t, s))$$

for any solution  $u(t, s)$  of (4.7). Hence, we obtain easily the following auxiliary theorem which is our principal tool.

**Auxiliary theorem.** *Under the conditions mentioned above, let the inequality*

$$(4.8) \quad \sum_{i=1}^m P_i(x) \partial_i \omega(x) \geq \frac{1}{\omega(x)} \sum_{\nu=1}^m Q_\nu(x, u) \cdot u_\nu$$

*hold for any  $x \in X$  such that  $|u| = \omega(x)$ . Then, for any function  $B(s) = (B_1(s), \dots, B_l(s))$  of class  $C^1$  on  $S$  such that*

---

1) an  $(m, m)$ -determinant.

$$(4.9) \quad |B(s)| \leq \omega(A(s)),$$

there exists a unique solution  $u(x)$  of (4.1) on  $X$ , such that

$$u(A(s)) = B(s)$$

and

$$(4.10) \quad |u(x)| \leq \omega(x)$$

for  $x \in X$ .

#### § 4. Estimation of $u(x)$ .

5. Consider the system of partial differential equations

$$(5.1) \quad \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij}x_j + f_i(x) \right) \partial_i u_\nu = \sum_{\mu=1}^m a_{\nu\mu} \cdot u_\mu + g_\nu(x) \quad (\nu = 1, \dots, m)$$

for which we have the following lemma.

**Lemma.** Let  $A = (a_{ij})$  and  $f(x)$  satisfy the assumptions (i), (ii) and (iii) in the theorem. Let  $g_\nu(x)$  ( $\nu = 1, \dots, m$ ) be real-valued functions of class  $C^1$  on some neighborhood of 0, such that

$$(5.2) \quad \begin{cases} g(0) = 0 \\ |\partial_x g(x)| \leq G|x|^p \end{cases}$$

where  $G$  and  $p$  are positive constants.

Then there exists a constant  $h_0 > 0$ , which depends only on  $\lambda_i$  ( $i = 1, \dots, m$ ), with the following property: if  $p > h_0$ , the system (5.1) has a unique solution  $u(x)$  in a neighborhood of 0, such that

$$(5.3) \quad u(x) = 0 \quad \text{on the cone} \quad \sum_{i=1}^k x_i^2 = \sum_{i=k+1}^m x_i^2$$

and

$$(5.4) \quad |\partial_x u(x)| \leq C \cdot G|x|^p$$

where  $C$  is a positive constant depending only on  $\lambda_i$  ( $i = 1, \dots, m$ ) and  $p$ .

6. *Proof.* By setting  $P_i(x) = \sum_{j=1}^m a_{ij}x_j + f_i(x)$  and  $Q_\nu(x, u) = \sum_{\mu=1}^m a_{\nu\mu}u_\mu + g_\nu(x)$ , the system (5.1) has the form (4.1). Without loss of generality we assume that  $A = (a_{ij})$  has the following form:

$$(i) \quad \begin{array}{ll} a_{ii} = \Re(\lambda_i) & (i = 1, \dots, m), \\ \Re(\lambda_i) > 0 & \text{for } i \leq k, \\ \Re(\lambda_i) < 0 & \text{for } i > k. \end{array}$$

---

2) Cf. (i)  $k=0$  means  $\Re(\lambda_i) < 0$  for all  $i$ , and  $k=m$  means  $\Re(\lambda_i) > 0$  for all  $i$ .

$$(ii) \quad \begin{aligned} a_{ij} &= 0 && \text{for } i \leq k \text{ and } j > k, \\ a_{ij} &= 0 && \text{for } i > k \text{ and } j \leq k. \end{aligned}$$

(iii)

$$(6.1) \quad \left| \sum_{i \neq j} a_{ij} x_i x_j \right| \leq \delta |x|^2$$

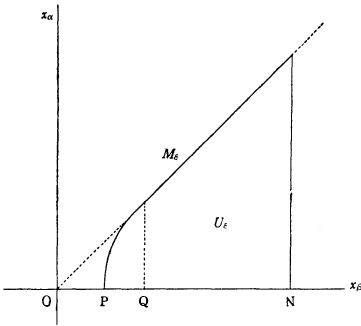
where  $\delta$  is any prescribed positive number.

In what follows, we write  $\sum_{\alpha} = \sum_{\alpha=1}^k$  and  $\sum_{\beta} = \sum_{\beta=k+1}^m$ . We suppose that  $f$  and  $g$  are functions of class  $C^1$  on  $U = \{x : \sum_{\alpha} x_{\alpha}^2 \leq r^2, \sum_{\beta} x_{\beta}^2 \leq r^2\}$  where  $r$  is a positive constant. We consider the case  $0 < k < m$ . Because, if  $k=0$  or  $k=m$ , the proof of the lemma will be simpler.

With sufficiently small  $\varepsilon > 0$  we set<sup>3)</sup>

$$(6.2) \quad S_{\varepsilon}(x) = \begin{cases} \sum_{\alpha} x_{\alpha}^2 - \sum_{\beta} x_{\beta}^2 & \text{when } \sum_{\alpha} x_{\alpha}^2 \geq \varepsilon^2 \\ \sum_{\alpha} x_{\alpha}^2 - \sum_{\beta} x_{\beta}^2 - \frac{1}{2\varepsilon^2} (\varepsilon^2 - \sum_{\alpha} x_{\alpha}^2)^2 & \text{when } \sum_{\alpha} x_{\alpha}^2 < \varepsilon^2, \end{cases}$$

and define a bounded region  $U_{\varepsilon}$  by  $U_{\varepsilon} = \{x \in U : S_{\varepsilon}(x) \geq 0\}$ .



$$\begin{aligned} N &= (r, 0) \\ P &= \left( \frac{\sqrt{6} - \sqrt{2}}{2} \varepsilon, 0 \right) \\ Q &= (\varepsilon, 0) \end{aligned}$$

First we consider the solution of (5.1) in  $U_{\varepsilon}$  vanishing on the  $(m-1)$ -dimensional manifold  $M_{\varepsilon} = \{x \in U : S_{\varepsilon}(x) = 0\}$ . For the base characteristic  $x = x(t)$  of (5.1), we have

$$\begin{aligned} \frac{1}{2} \cdot \frac{d}{dt} S_{\varepsilon}(x(t)) &= \sum_{\alpha} x_{\alpha} \cdot \dot{x}_{\alpha} - \sum_{\beta} x_{\beta} \cdot \dot{x}_{\beta} \\ &= \sum_{\alpha} \left( \sum_{i=1}^m a_{\alpha i} x_i + f_{\alpha}(x) \right) x_{\alpha} - \sum_{\beta} \left( \sum_{i=1}^m a_{\beta i} x_i + f_{\beta}(x) \right) x_{\beta} \\ &= \left( \sum_{\alpha} \sum_{i=1}^m a_{\alpha i} x_{\alpha} x_i - \sum_{\beta} \sum_{i=1}^m a_{\beta i} x_{\beta} x_i \right) + \left( \sum_{\alpha} f_{\alpha}(x) x_{\alpha} - \sum_{\beta} f_{\beta}(x) x_{\beta} \right) > 0 \end{aligned}$$

3) For the case  $k=0$  or  $k=m$ , we have to set  $S_{\varepsilon}(x) = \sum_{i=1}^m x_i^2$ .

when  $\varepsilon^2 < \sum_{\alpha} x_{\alpha}^2 \leq r^2$ , by taking  $r$  small enough, and also when  $\sum_{\alpha} x_{\alpha}^2 \leq \varepsilon^2$

$$\frac{1}{2} \cdot \frac{d}{dt} S_{\varepsilon}(x(t)) = \left\{ 1 + \frac{1}{\varepsilon^2} (\varepsilon^2 - \sum_{\alpha} x_{\alpha}^2) \right\} \sum_{\alpha} x_{\alpha} \cdot \dot{x}_{\alpha} - \sum_{\beta} x_{\beta} \cdot \dot{x}_{\beta} > 0.$$

From these inequalities we see that, if  $r > 0$  is taken small enough, every base characteristic of (5.1) meeting  $M_{\varepsilon}$  is transverse to  $M_{\varepsilon}$ , and that (4.5) will hold for this case with  $M = M_{\varepsilon}$ . In addition, since we have

$$\frac{1}{2} \frac{d}{dt} \sum_{\alpha} (x_{\alpha}(t))^2 = \sum_{\alpha} (\sum_i a_{\alpha i} x_i + f_{\alpha}(x)) x_{\alpha} > 0$$

for any base characteristic  $x(t)$ , when  $r$  is small enough, we see that  $U_{\varepsilon}$  is filled up only onefold with the base characteristics issuing from  $M_{\varepsilon}$ . Therefore, we apply the auxiliary theorem to this case, setting  $U_{\varepsilon} = X$ .

We set

$$(6.3) \quad \varphi(x) = (1 + \gamma) \sum_{\alpha} x_{\alpha}^2 - \sum_{\beta} x_{\beta}^2$$

and

$$(6.4) \quad \omega(x) = W \cdot G \cdot \varphi(x)^{\frac{p+1}{2}}$$

where  $\gamma > 0$  and  $W > 0$  will be determined later. Then

$$(6.5) \quad \frac{\gamma}{2} |x|^2 \leq \varphi(x) \leq (1 + \gamma) |x|^2$$

for every  $x \in U_{\varepsilon}$ . Thus we obtain

$$\begin{aligned} & \sum_{i=1}^m P_i(x) \partial_i \omega(x) \\ &= (p+1) \cdot W \cdot G \cdot \varphi(x)^{\frac{p-1}{2}} \left\{ (1 + \gamma) \sum_{\alpha} \sum_j a_{\alpha j} x_{\alpha} x_j - \sum_{\beta} \sum_j a_{\beta j} x_{\beta} x_j \right. \\ & \quad \left. + (1 + \gamma) \sum_{\alpha} x_{\alpha} f_{\alpha}(x) - \sum_{\beta} x_{\beta} f_{\beta}(x) \right\} \end{aligned}$$

and

$$\sum_{\nu=1}^m Q_{\nu}(x, u) \cdot u_{\nu} = \sum_{\nu=1}^m \sum_{\mu=1}^m a_{\nu \mu} u_{\nu} u_{\mu} - \sum_{\nu=1}^m g_{\nu}(x) u_{\nu}.$$

Now we set

$$(6.6) \quad \Lambda_0 = \min_{1 \leq i \leq m} |\Re(\lambda_i)|, \quad \Lambda_1 = \max_{1 \leq i \leq m} |\Re(\lambda_i)|.$$

Then we have

$$(6.7) \quad \sum_{i=1}^m P_i(x) \cdot \partial_i \omega(x) > (p+1)(\Lambda_0 - 2\delta) W \cdot G |x|^2 \varphi(x)^{\frac{p-1}{2}}$$



and

$$(6.8) \quad \sum_{\nu=1}^m Q_{\nu}(x, u) \cdot u_{\nu} < (\Lambda_1 + \delta) |u|^2 + |g(x)| \cdot |u|$$

on  $U_{\varepsilon}$  where  $\delta$  is given by (6.1), taking  $r$  small enough. From (6.8) it follows that, if  $|u| = \omega(x)$  for some  $x \in U_{\varepsilon}$ , then

$$\frac{1}{\omega(x)} \sum_{\nu=1}^m Q_{\nu}(x, u) u_{\nu} < (\Lambda_1 + \delta) \omega(x) + G |x|^{\rho+1}$$

and so

$$(6.9) \quad \frac{1}{\omega(x)} \sum_{\nu=1}^m Q_{\nu}(x, u) u_{\nu} < W \cdot G (\Lambda_1 + \delta) \left\{ 1 + \gamma + \left( \frac{2}{\Lambda_1 \cdot W} \right)^{\frac{\rho-1}{2}} \right\} |x|^2 \varphi(x)^{\frac{\rho-1}{2}}$$

by virtue of (6.4) and (6.5). Thus, if we assume

$$(6.10) \quad (\rho + 1) \Lambda_0 > \Lambda_1,$$

we have

$$(6.11) \quad \sum_{i=1}^m P_i(x) \partial_i \omega(x) > \frac{1}{\omega(x)} \sum_{\nu=1}^m Q_{\nu}(x, u) \cdot u_{\nu}$$

for any  $x \in U_{\varepsilon}$  such that  $|u| = \omega(x)$ , from (6.7) and (6.9), by taking  $\delta > 0$  and  $\gamma > 0$  small enough and then  $W$  large enough.

Let us assume hereafter that (6.10) holds. Then it follows from the auxiliary theorem that, when  $r$  is small enough, there exists a unique solution  $u(x; \varepsilon)$  of (5.1) on  $U_{\varepsilon}$  which vanishes on  $M_{\varepsilon}$ , and that it satisfies

$$(6.12) \quad |u(x; \varepsilon)| \leq \omega(x) = W \cdot G \cdot \varphi(x)^{\frac{\rho+1}{2}} \leq G \cdot K \cdot |x|^{\rho+1} \quad \text{for } x \in U_{\varepsilon}$$

where  $K = W(1 + \gamma)^{\frac{\rho+1}{2}}$ . Notice that  $W$  and  $r$  are taken independent of  $\varepsilon > 0$  in the above argument.

### § 5. Continuation of the Proof of the Lemma.

#### Estimation of $|\partial_x u(x)|$ .

7. Next, let us prove that the inequality (5.4) holds for  $u = u(x; \varepsilon)$  on  $U_{\varepsilon}$  with some constant  $C > 0$  independent of  $\varepsilon$ . In this paragraph we fix  $\varepsilon > 0$  and write  $u_{\nu}(x)$  in place of  $u_{\nu}(x; \varepsilon)$  for simplicity.

In order to estimate  $|\partial_x u(x)|$  on the manifold  $M_{\varepsilon}$ , we reduce the system (5.1) into

$$(7.1) \quad \frac{du_{\nu}}{dt} = \sum_{\mu=1}^m a_{\nu\mu} u_{\mu} + g_{\nu}(x(t, s)) \quad (\nu = 1, \dots, m)$$

by the change of variables given by (4.6). Thus, if we set  $u_v(t, s) = u_v(x(t, s))$ ,  $u = u(t, s)$  is the solution of (7.1) with the initial condition

$$(7.2) \quad u(0, s) \equiv 0.$$

Therefore,

$$(7.3) \quad \begin{cases} \partial_t u(0, s) \equiv g(x(0, s)) \\ \partial_s u(0, s) \equiv 0 \end{cases}$$

on  $M_\varepsilon$ . Let  $\partial_n u(s)$  denote the normal derivative of  $u(t, s)$  at  $x = x(0, s)$  on  $M_\varepsilon$ , then we have

$$(7.4) \quad \left[ \frac{\partial_t u(t, s)}{\left\{ \sum_{i=1}^m (\partial_t x_i(t, s))^2 \right\}^{\frac{1}{2}}} \right]_{t=0} = \partial_n u(s) \cdot \cos \theta(s)$$

where  $\theta(s)$  represents the angle between the base characteristic  $x = x(t, s)$  and the normal of  $M_\varepsilon$  at  $x(0, s)$ , i.e.

$$(7.5) \quad \cos \theta(s) = \frac{(1 + \sigma(x)) \cdot \sum_{\alpha} x_{\alpha} \cdot \partial_t x_{\alpha} - \sum_{\beta} x_{\beta} \cdot \partial_t x_{\beta}}{\left\{ \sum_{i=1}^m (\partial_t x_i)^2 \right\}^{\frac{1}{2}} \left\{ (1 + \sigma(x))^2 \sum_{\alpha} x_{\alpha}^2 + \sum_{\beta} x_{\beta}^2 \right\}^{\frac{1}{2}}}$$

where

$$\sigma(x) = \begin{cases} 0 & \text{when } \sum_{\alpha} x_{\alpha}^2 \geq \varepsilon^2 \\ \frac{1}{\varepsilon^2} (\varepsilon^2 - \sum_{\alpha} x_{\alpha}^2) & \text{when } \sum_{\alpha} x_{\alpha}^2 < \varepsilon^2. \end{cases}$$

Since

$$(7.6) \quad (1 + \sigma(x)) \cdot \sum_{\alpha} x_{\alpha} \cdot \partial_t x_{\alpha} - \sum_{\beta} x_{\beta} \cdot \partial_t x_{\beta} > \frac{1}{2} \Lambda_0 |x|^2 \quad (x \in U_\varepsilon)$$

and

$$(7.7) \quad (1 + \sigma(x))^2 \cdot \sum_{\alpha} x_{\alpha}^2 + \sum_{\beta} x_{\beta}^2 < 2|x|^2,$$

when  $r$  is sufficiently small, we obtain, from (7.3), (7.4), (7.5), (7.6) and (7.7),

$$|\partial_n u| < \frac{2\sqrt{2}}{\Lambda_0} \cdot \frac{|g(x)|}{|x|}.$$

Hence

$$(7.8) \quad |\partial_n u| < K' \cdot G |x|^p$$

on  $M_\varepsilon$  with some constant  $K' > 0$  independent of  $\varepsilon$ . Thus, from (7.3) and (7.8), we see

$$(7.9) \quad |\partial_x u(x; \varepsilon)| \leq K' \cdot G |x|^p \quad (x \in M_\varepsilon).$$

Now, operating  $\partial_\mu$  on both sides of (5.1) and setting  $\partial_\mu u_\nu = u^{\nu\mu}$ , we have

$$(7.10) \quad \begin{aligned} & \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i(x) \right) \partial_i u^{\nu\mu} \\ &= \sum_{j=1}^m a_{\nu j} u^{j\mu} - \sum_{i=1}^m (a_{i\mu} + \partial_\mu f_i(x)) u^{\nu i} + \partial_\mu g_\nu(x) \quad (\nu, \mu = 1, \dots, m) \end{aligned}$$

which has also the form (4.1) with unknown functions  $u^{\nu\mu}$ . Let us assume first that  $f$  and  $g$  are functions of class  $C^2$  in  $U$  and apply the auxiliary theorem to (7.10). We set

$$u' = (u^{1,1}, u^{1,2}, \dots, u^{m,m}) \quad (\in R^{m^2})$$

$$P_i(x) = \sum_{j=1}^m a_{ij} x_j + f_i(x)$$

$$Q^{\nu\mu}(x, u') = \sum_{j=1}^m a_{\nu j} u^{j\mu} - \sum_{i=1}^m (a_{i\mu} + \partial_\mu f_i(x)) \cdot u^{\nu i} + \partial_\mu g_\nu(x) \quad (\nu, \mu = 1, \dots, m)$$

and  $\omega'(x) = W' \cdot G \cdot \varphi'(x)^{\frac{p}{2}}$  where  $\varphi'(x) = (1 + \gamma') \sum_{\alpha} x_{\alpha}^2 - \sum_{\beta} x_{\beta}^2$ .

Then, if we assume

$$(7.11) \quad p\Lambda_0 > \tilde{\Lambda} \equiv \max_{i,j} |\Re(\lambda_i) - \Re(\lambda_j)|,$$

and if we take  $r$  small enough, we have

$$\sum_{i=1}^m P_i(x) \partial_i \omega'(x) > \frac{1}{\omega'(x)} \sum_{\nu=1}^m \sum_{\mu=1}^m Q^{\nu\mu}(x, u') \cdot u^{\nu\mu}$$

for  $x$  such that  $\omega'(x) = |u'|$  in  $U_\varepsilon$ , taking  $W'$  and  $\gamma' > 0$  appropriately. By the auxiliary theorem and (7.9) we thus get

$$(7.12) \quad |\partial_x u(x; \varepsilon)| \leq C \cdot G |x|^p$$

in  $U_\varepsilon$  where  $C > 0$  is a constant independent of  $\varepsilon$ . In the above consideration we can also choose  $r$  independent of  $\varepsilon$ . Let us write

$$h_0 = \max \left( \frac{\Lambda_1}{\Lambda_0} - 1, \tilde{\Lambda} \right)$$

and assume  $p > h_0$  hereafter, from which (6.10) and (7.11) follow.

We will study in 9. as to the case that  $f$  and  $g$  are functions of class  $C^1$ .

8. Notice that  $C$  of (7.12) and  $r$  can be chosen independent of  $\varepsilon > 0$  which is sufficiently small. Now we consider  $\varepsilon$  as a variable tending to zero. We see easily  $U_\varepsilon \subset U_{\varepsilon'}$  as  $\varepsilon > \varepsilon' > 0$ , and  $v = u(x; \varepsilon') - u(x; \varepsilon)$  must satisfy on  $U_\varepsilon$

$$(8.1) \quad \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i(x) \right) \partial_i v_\nu = \sum_{\mu=1}^m a_{\nu\mu} v_\mu \quad (\nu = 1, \dots, m).$$

From (6.12) and (7.12) we see easily that

$$|v| \leq 2^{\frac{p+3}{2}} K \cdot G \cdot \varepsilon^{p+1}$$

and

$$|\partial_x v| \leq 2^{\frac{p+2}{2}} C \cdot G \cdot \varepsilon^p$$

hold for  $v = u(x; \varepsilon') - u(x; \varepsilon)$  on  $M_\varepsilon$ . Notice that  $\min_{x \in U_\varepsilon} |x| = \frac{\sqrt{6} - \sqrt{2}}{2} \varepsilon$ , and we have for any  $q > 0$

$$(8.2) \quad \begin{cases} |v| \leq K_0 \cdot \varepsilon^{p-q} |x|^{q+1} \\ |\partial_x v| \leq K_1 \cdot \varepsilon^{p-q} |x|^q \end{cases}$$

on  $M_\varepsilon$  where  $K_0$  and  $K_1$  are constants not depending on  $\varepsilon$  and  $\varepsilon'$ .

We now choose  $q$  so that  $p > q > h_0$ . The system (8.1) is a special case of (5.1) with  $g(x) \equiv 0$ , and we get similarly as (6.12) and (7.12)

$$\begin{cases} |u(x; \varepsilon') - u(x; \varepsilon)| \leq K' \cdot \varepsilon^{p-q} |x|^{q+1} \\ |\partial_x u(x; \varepsilon') - \partial_x u(x; \varepsilon)| \leq K' \cdot \varepsilon^{p-q} |x|^q \end{cases}$$

in  $U_\varepsilon$  where  $K'$  is some positive constant independent of  $\varepsilon$  and  $\varepsilon'$ . Thus we see that, as  $\varepsilon \rightarrow 0$ ,  $u_\nu(x; \varepsilon)$  and  $\partial_\mu u_\nu(x; \varepsilon)$  tend to certain functions  $u_\nu(x)$  and their derivatives  $\partial_\mu u_\nu(x)$  respectively. Clearly this  $u(x)$  is a solution of (5.1), vanishing on the manifold:  $\sum_\alpha x_\alpha^2 = \sum_\beta x_\beta^2$  and satisfying (5.4) in  $U_1 = \{x : \sum_\alpha x_\alpha^2 \leq r^2, \sum_\beta x_\beta^2 \leq \sum_\alpha x_\alpha^2\}$ .

Quite similarly as above, we can prove the existence of a solution  $u(x)$  of (5.1) vanishing on  $\sum_\alpha x_\alpha^2 = \sum_\beta x_\beta^2$  and satisfying (5.4) in  $U_2 = \{x : \sum_\beta x_\beta^2 \leq r^2, \sum_\alpha x_\alpha^2 \leq \sum_\beta x_\beta^2\}$ .

9. Now it remains to prove our lemma when  $f$  and  $g$  are functions of class  $C^1$ . We construct approximation sequences  $\{f^n(x)\}_{n=1}^\infty$  and  $\{g^n(x)\}_{n=1}^\infty$  of vector functions of class  $C^2$  such that<sup>4)</sup>

$$(9.1) \quad \begin{cases} f^n(0) = g^n(0) = 0 \\ f^n(x) = p(x) + q^n(x)^{5)} \\ |\partial_x f^n(x) - \partial_x f(x)| \leq \frac{1}{n} |x|^h \\ |\partial_x g^n(x) - \partial_x g(x)| \leq \frac{1}{n} |x|^h. \end{cases}$$

4)  $f^n(x)$  and  $g^n(x)$  have only to be of class  $C^2$  in  $U$  excepting  $x=0$ .

5) c. f. (2.1).

Then there exists a system  $u^n(x) = (u_1^n(x), \dots, u_m^n(x))$  of functions of class  $C^2$  satisfying

$$(9.2) \quad \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i^n(x) \right) \partial_i u_\nu = \sum_{\mu=1}^m a_{\nu\mu} u_\mu + g_\nu^n(x) \quad (\nu = 1, \dots, m),$$

such that

$$\begin{cases} |u^n(x)| \leq C \cdot K_2 |x|^{\rho+1} \\ |\partial_x u^n(x)| \leq C \cdot K_3 |x|^\rho \end{cases}$$

in  $U$  where  $K_2$  and  $K_3$  are constants not depending on  $n$ . For  $u^n(x) - u^{n'}(x)$  ( $n \leq n'$ ) we have

$$\sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i^n(x) \right) \partial_i (u_\nu^n - u_\nu^{n'}) = \sum_{\mu=1}^m a_{\nu\mu} (u_\mu^n - u_\mu^{n'}) + h_\nu^{n,n'}(x),$$

where  $h_\nu^{n,n'}(x) = \{g_\nu^n(x) - g_\nu^{n'}(x)\} + \partial_i u_\nu^{n'} \{f_i^n(x) - f_i^{n'}(x)\}$

and so  $h^{n,n'}(0) = 0$  and  $|\partial_x h^{n,n'}(x)| \leq \frac{H}{n} |x|^\rho$

with a constant  $H > 0$  not depending on  $n$  and  $n'$ . Therefore we see that, as  $n \rightarrow \infty$ ,  $u^n(x)$  tend to the desired solution of (5.1). The proof of the lemma is thus completed.

### § 6. Proof of the Main Theorem.

10. Let us now turn to the system (3.1),

$$\sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i(x) \right) \partial_i u_\nu = \sum_{\mu=1}^m a_{\nu\mu} u_\mu - f_\nu(x) \quad (\nu = 1, \dots, m)$$

where  $f_\nu(x) = p_\nu(x) + q_\nu(x)$ . First, let us consider

$$(10.1) \quad \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + p_i(x) \right) \partial_i u_\nu = \sum_{\mu=1}^m a_{\nu\mu} u_\mu - p_\nu(x) \quad (\nu = 1, \dots, m).$$

If there exist no relations of the form  $\lambda_i = \sum_j n_j \lambda_j$  where  $n_j$  are non-negative integers such that  $\sum_j n_j > 1$ , we can construct infinite series of the form

$$\sum_{\substack{p_i \geq 0 \\ p_1 + \dots + p_m \geq 2}} c_{p_1, \dots, p_m}^\nu \cdot x_1^{p_1} \cdot \dots \cdot x_m^{p_m}$$

with real coefficients  $c_{p_1, \dots, p_m}^\nu$ , such that  $u_\nu = \sum c_{p_1, \dots, p_m}^\nu \cdot x_1^{p_1} \cdot \dots \cdot x_m^{p_m}$  ( $\nu = 1, \dots, m$ ) satisfy (10.1) formally. To see this, make a change of variables,  $x = T \cdot y$  and  $u = T \cdot w$ , by a (complex) matrix  $T$  transforming  $A = (a_{ij})$  into Jordan's canonical form  $T^{-1} \cdot A \cdot T$ , and consider about the (complex) system thus obtained.

Setting

$$(10.2) \quad \dot{u}_\nu(x) = \sum_{2 \leq p_1 + \dots + p_m \leq h} c_{p_1 \dots p_m}^\nu \cdot x_1^{p_1} \dots x_m^{p_m} \quad (\nu = 1, \dots, m)$$

and

$$(10.3) \quad \dot{\bar{u}}_\nu = u_\nu - \dot{u}_\nu(x) \quad (\nu = 1, \dots, m),$$

we reduce (3.1) to the system

$$(10.4) \quad \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i(x) \right) \partial_i \dot{\bar{u}}_\nu = \sum_{\mu=1}^m a_{\nu\mu} \dot{u}_\mu + \tilde{f}_\nu(x) \quad (\nu = 1, \dots, m)$$

where

$$\tilde{f}_\nu(x) = \sum_{\mu=1}^m a_{\nu\mu} \dot{u}_\mu(x) - \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + f_i(x) \right) \partial_i \dot{u}_\nu(x) - f_\nu(x).$$

In order to define  $\dot{u}(x)$  as above, we have only to assume that condition (iii) in the theorem (§ 2) is satisfied.

By (2.1) we have

$$(10.5) \quad \tilde{f}_\nu(x) = \tilde{p}_\nu(x) - \tilde{q}_\nu(x)$$

where 
$$\tilde{p}_\nu(x) = \sum_{\mu=1}^m a_{\nu\mu} \dot{u}_\mu(x) - p_\nu(x) - \sum_{i=1}^m \left( \sum_{j=1}^m a_{ij} x_j + p_i(x) \right) \partial_i \dot{u}_\nu(x)$$

and 
$$\tilde{q}_\nu(x) = q_\nu(x) + \sum_{i=1}^m q_i(x) \partial_i \dot{u}_\nu(x),$$

and it follows from the definition of  $\dot{u}(x)$  that  $\tilde{p}_\nu(x)$ , polynomials in  $x_i$  ( $i=1, \dots, m$ ), contain no terms of degree  $\leq h$ . Therefore, by (2.2)

$$\begin{cases} \tilde{f}_\nu(0) = 0 & (\nu = 1, \dots, m), \\ |\partial_x \tilde{f}(x)| \leq \tilde{K} \cdot |x|^h \end{cases}$$

where  $\tilde{K}$  is a positive constant. Using the lemma, we thus see that there exists a solution  $\dot{\bar{u}}(x) = (\dot{\bar{u}}_1(x), \dots, \dot{\bar{u}}_m(x))$  of (10.4) in some neighborhood of  $x=0$ , such that

$$\dot{\bar{u}}_i(0) = 0 \quad (i = 1, \dots, m)$$

and

$$|\partial_x \dot{\bar{u}}(x)| \leq C \cdot \tilde{K} |x|^h$$

with some constant  $C > 0$ . We set

$$u_\nu(x) = \dot{u}_\nu(x) + \dot{\bar{u}}_\nu(x) \quad (\nu = 1, \dots, m)$$

and obtain those functions  $u_\nu(x)$  ( $\nu=1, \dots, m$ ) whose existence was claimed

in the theorem. The proof of the theorem is thus completed.

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